

SGDH-□, SGMBH-□

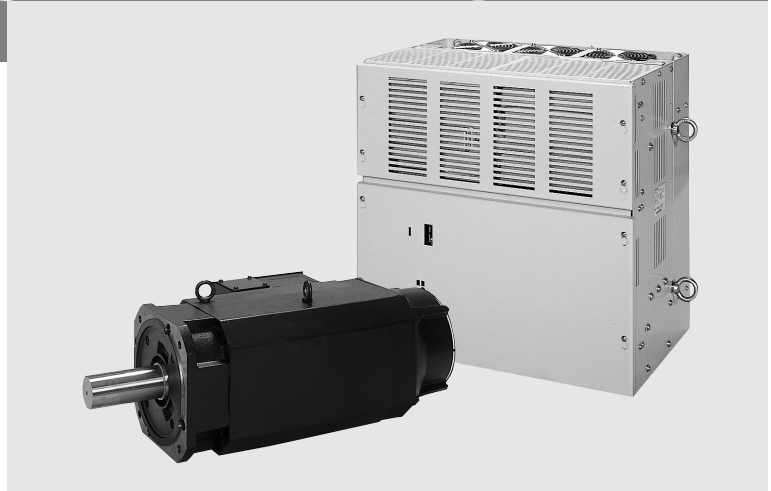
Sigma-II Large Capacity

Large Capacity Sigma-II series. Great power as well as High Speed, and High Accuracy.

- Easy setup and maintenance
- Optional Units for system flexibility and connectivity
- Automatic motor recognition
- Analogue control for speed and torque
- Pulse train control for positioning
- Oscilloscope available via SigmaWin tool
- Windows based Configuration and commissioning software

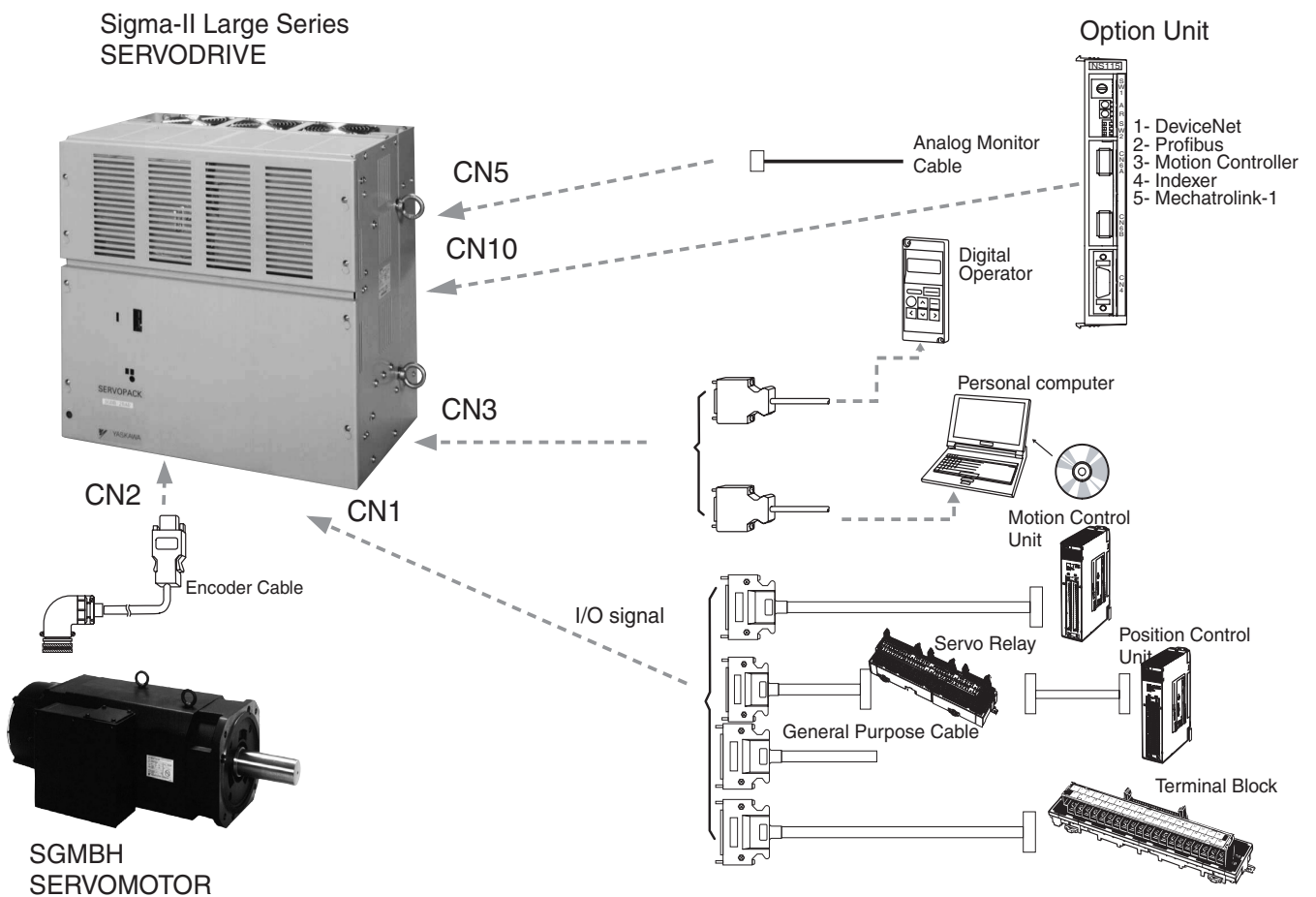
Ratings

- 400 VAC, 22 kW (140 Nm) to 55 kW (350 Nm)



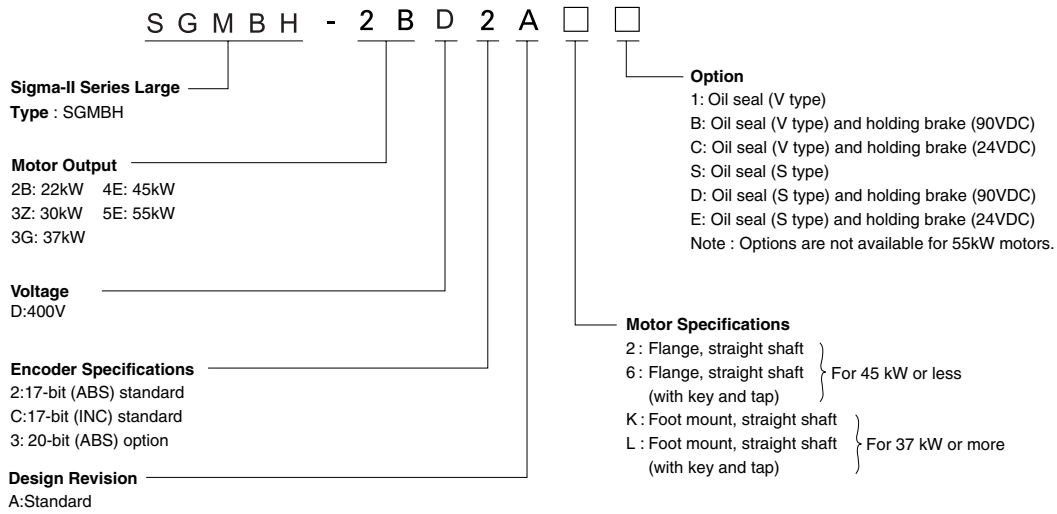
AC Servo Systems

System Configuration



Servomotor Specifications

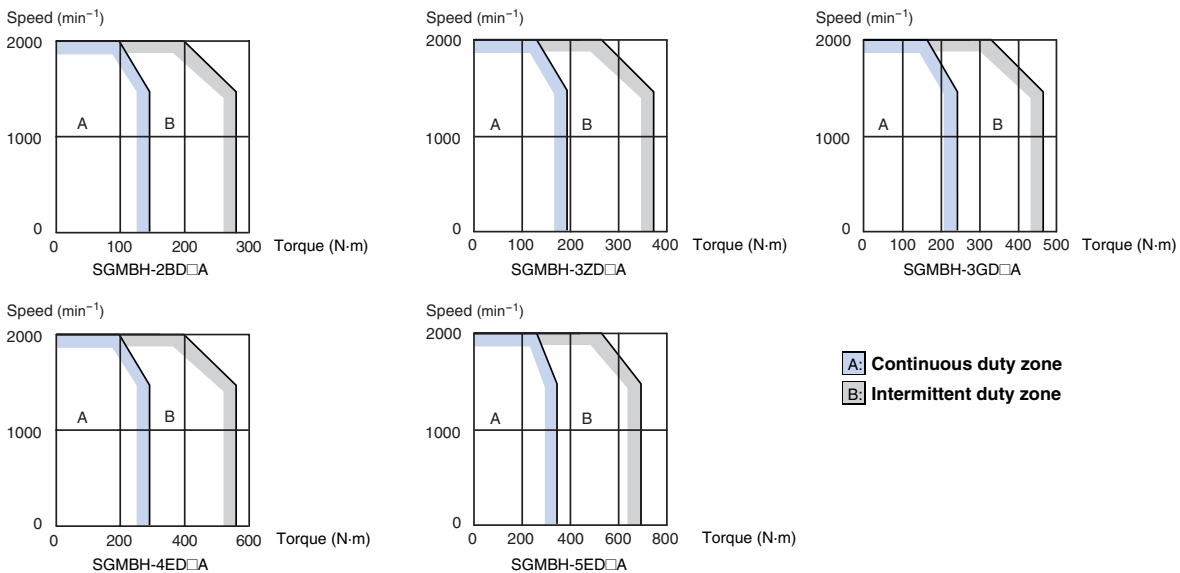
Type Designation



Type	SGMBH-□	2BD□A	3ZD□A	3GS□A	4ED□A	5ED□A	
Performance	Rated Output	kW	22	30	37	45	55
	Rated Torque	N·m	140	191	236	286	350
	Stalling Torque	N·m	140	191	236	286	350
	Instantaneous Peak Torque	N·m	280	382	471	572	700
	Rated Current	A(rms)	58	80	100	127	150
	Instantaneous Max. Current	A(rms)	120	170	210	260	310
	Rated/Max. Speed	min⁻¹	1500/2000				
	Rotor Inertia	kg·m²	0.0592	0.0773	0.139	0.151	0.197
Structure	Protective Enclosure	IP44					
	Mounting Method	Flange		Flange Foot mount ¹		Foot mount	
Encoder	Standard	Incremental, absolute: 17 bits 16384P/R or equivalent ²					
	Option	Absolute: 20 bits 16384P/R or equivalent					
Usage Temperature	0 to 40°C						
Usage Humidity	20 to 80% (non-condensing)						

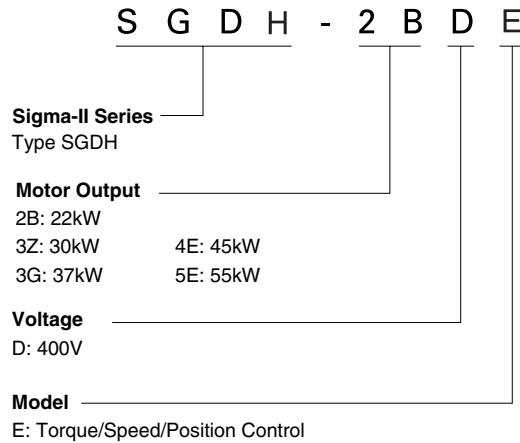
- Note:** 1. 37 kW and 45 kW motors with brakes are foot mount type
 2. The number of output pulses of SERVOPACK is 16384P/R for both 17-bit and 20-bit encoders (no dividing).

Torque/Speed Characteristics



Servo Drive Specifications

Type Designation



AC Servo Systems

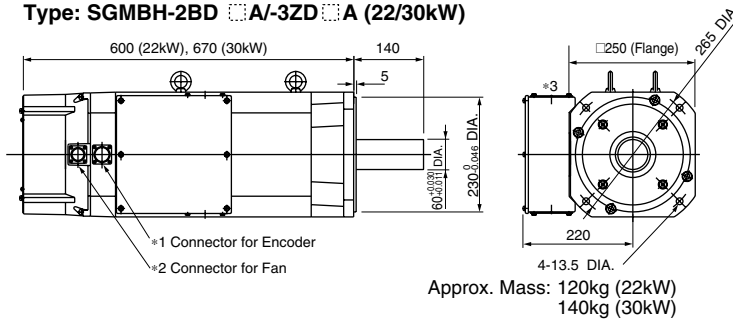
Type	SGDH-□	2BDE	3ZDE	3GDE	4EDE	5EDE	
Applicable SERVOMOTOR Type	SGBH-□	2BD□A	3ZD□A	3GD□A	4ED□A	5ED□A	
Continuous Output	kW	22	30	37	45	55	
Allowable Load Inertia	kg · m ² x 10	0.296	0.3865	0.695	0.840	0.985	
Basic Specifications	Power Supply	Main Circuit	Three-phase 380 to 480VAC/+10 to -15%, 50/60Hz				
		Main Circuit Power Capacity kVA	36.7	50.1	61.8	75.2	91.9
		Control Circuit	24VDC±10%				
		Control Circuit Power Capacity	150VA				
	Control method	Three-phase, full-wave rectification IGBT-PWM					
	Feedback	17-bit serial encoder (incremental/absolute)					
	Usage/Storage Temperature	SERVOPACK: 0 to 55°C / -20 to 85°C Digital operator: 0 to 55°C / -20 to 70°C					
	Usage/Storage Humidity	90%RH or less (non-condensing)					
	Control Method	Speed Control	±2 to ±10VDC at 155r/min				
		Torquer Control	±1 to ±10VDC at rated output				
		Position Control	Input form: Sign + pulse train, CD + CCW pulse train, 90° phase difference 2-phase pulse Input frequency: 500/200kpps (line driver/open collector output)				
	I/O Signals	Position Control	Output Form	Phase A, phase B, phase C: (line driver output)			
			Frequency Dividing Ratio	(16 to N) N: encoder pulse number			
		Sequence Input Signal	Servo ON, forward rotation prohibited (P-OT), reverse rotation prohibited (N-OT), forward rotation current limit, reverse rotation current limit, alarm reset, P control				
Sequence Output Signal		Servo alarm, 3-bit alarm code Select three signals from servo ready, current limit detection, TGON, positioning complete (speed agreement), brake release, overload, warning, overload detected					
Functions/Performance	Frequency Response	100Hz (motor inertia = load inertia)					
	DB	Built-in (External resistor is required)	External DB contactor and DB resistor are required.				
	Regeneration	Built-in (External resistor is required.)					
	Protection	Overcurrent, overload, regenerative error, main circuit voltage error, heatsink overheat, power open phase, overspeed, encoder error, encoder disconnected, overrun, CPU error, overflow, parameter error					
	Display	POWER, ALARM, CHARGE display LED 5-figure, 7-segment LED on digital operator					
	Others	Zero-clamp, soft start/stop. Reverse rotation connection, brake interlock signal output, JOG run					
	Digital Operator Type	JUSP-OP02A-2					
Mounting Method	Base mounted						

Note: DB means an automatic dynamic brake, which operates at main power OFF, servo alarm, servo OFF, and overtravel.

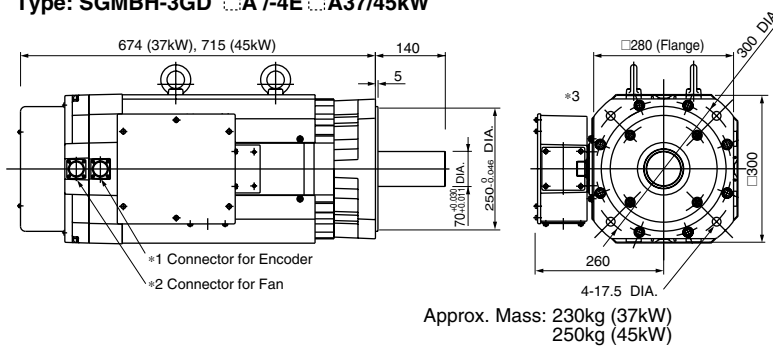
Dimensions

Servomotors

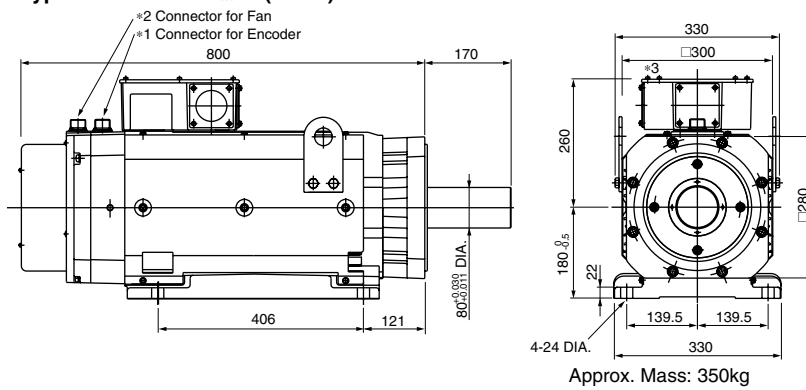
Type: SGMBH-2BD □A/-3ZD □A (22/30kW)



Type: SGMBH-3GD □A /-4E □A37/45kW

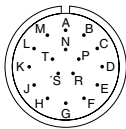


Type: SGMBH-5ED □A (55kW)

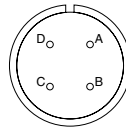


*1 Connector for Encoder

*2 Connector for Fan



Receptacle: 97F-3102E20-29P
Plug IP67 (L-shape): MS3108E20-29S



Receptacle: CE05-2A18-10PD-B
Plug IP67 (L-shape): MS3108E18-10S

● Absolute Encoder

A	—	K	—
B	—	L	—
C	DATA+	M	—
D	DATA-	N	—
E	—	P	—
F	—	R	—
G	0V	S	BATT-
H	+5VDC	T	BATT +
J	FG(Frame Ground)		

● Incremental Encoder

A	—	K	—
B	—	L	—
C	DATA+	M	—
D	DATA-	N	—
E	—	P	—
F	—	R	—
G	0V	S	—
H	+5VDC	T	—
J	FG(Frame Ground)		

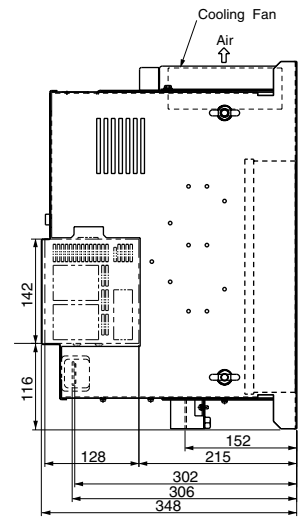
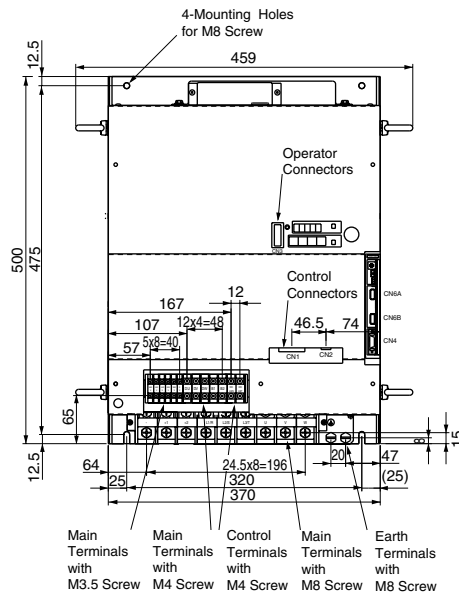
A	Fan Terminal (U)
B	Fan Terminal (V)
C	Fan Terminal (W)
D	

*3 Terminal Box

U, V, W,	Motor terminal	M10
⊕	Earth terminal	M10
1, 1b	Thermostat	M4

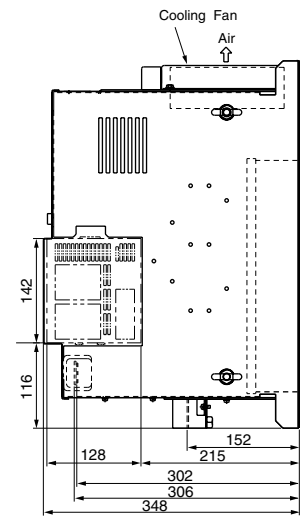
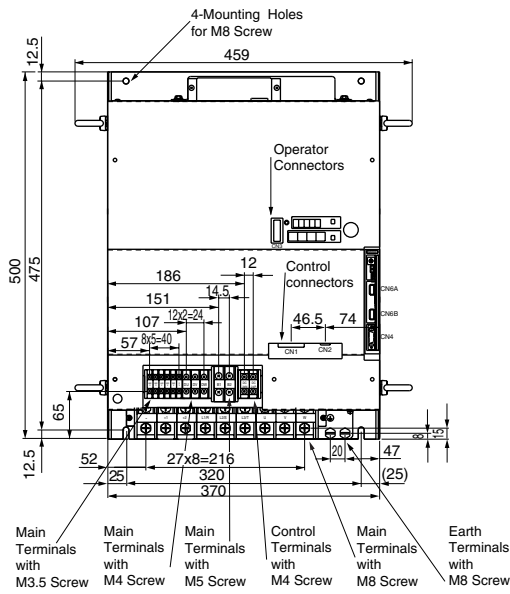
Servo Drives

Type: SGDH-2BDE (22kW)



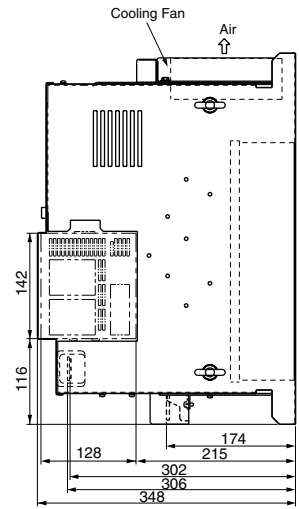
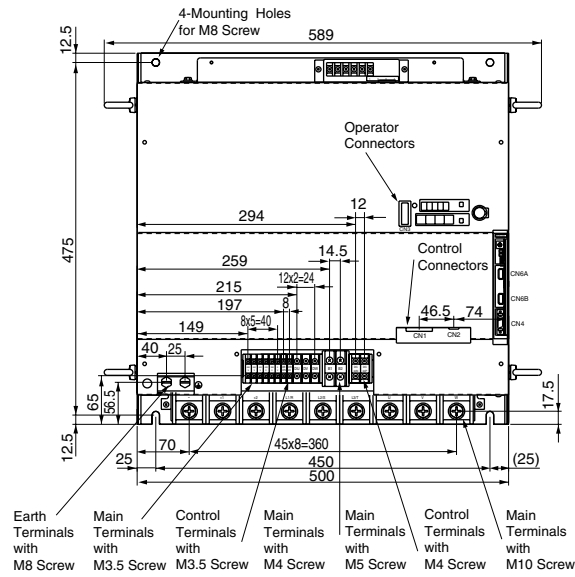
Approx. Mass: 40kg

Type: SGDH-3ZDE (30kW)



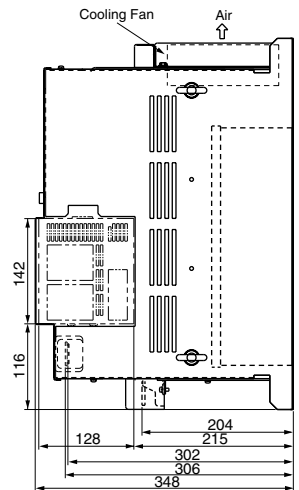
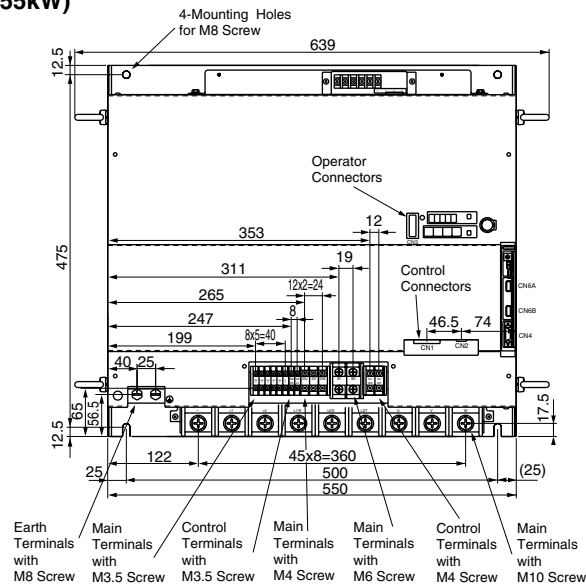
Approx. Mass: 40kg

Type: SGDH-3GDE (37kW)



Approx. Mass: 60kg

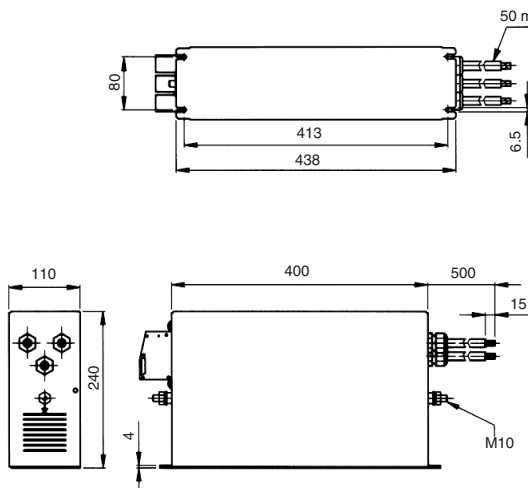
Type: SGDH-4EDE/-5EDE (45/55kW)



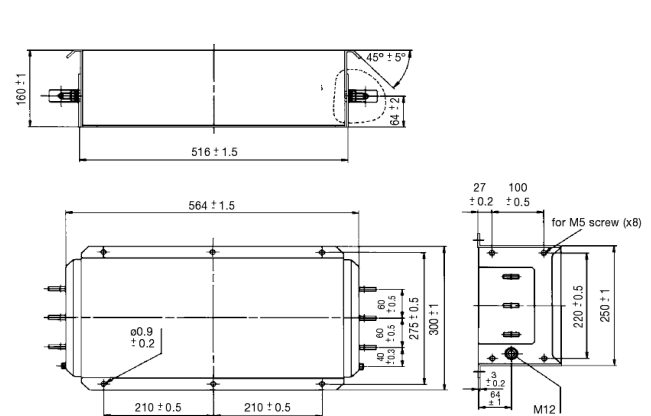
Approx. Mass: 65kg

Filters

FN258-180-07

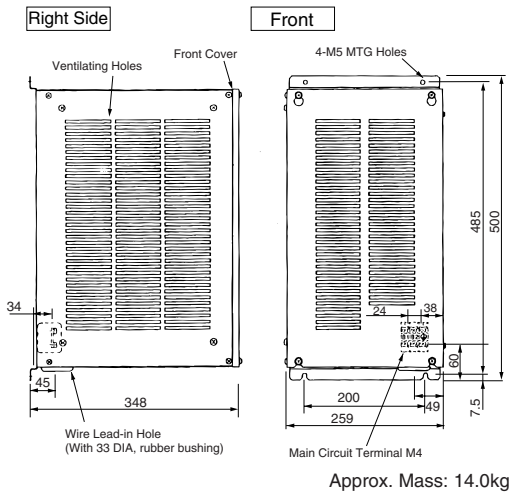


FN359-250-99

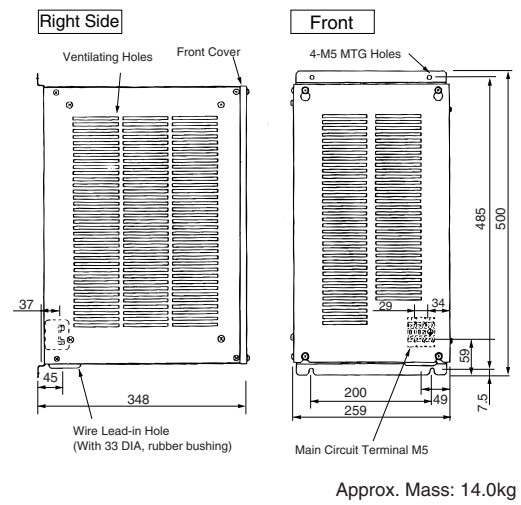


Regenerative Resistor Unit

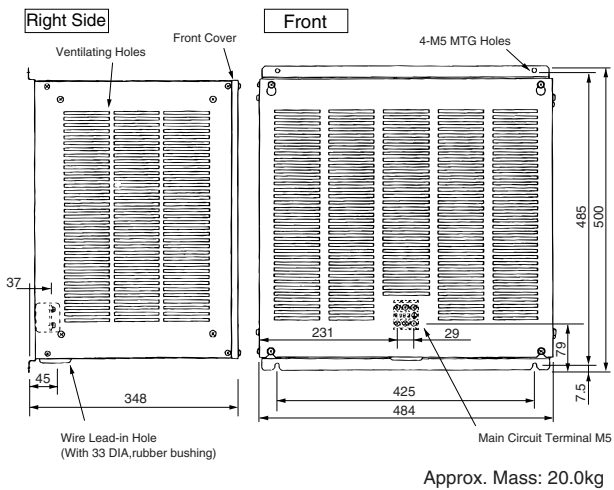
Type: JUSP-RA12 (for 22kW)



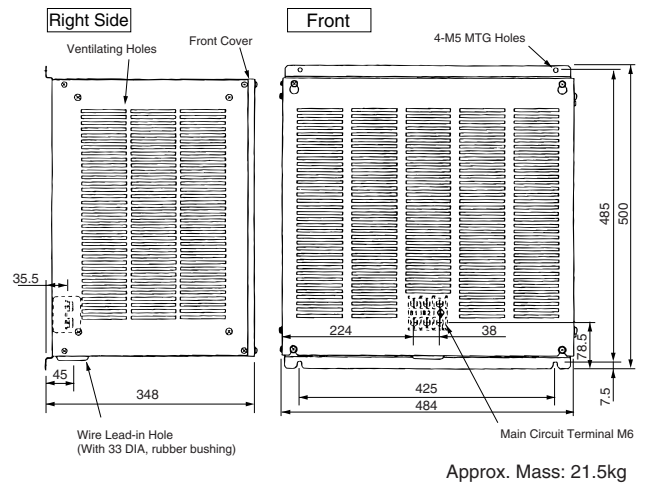
Type: JUSP-RA13 (for 30kW)



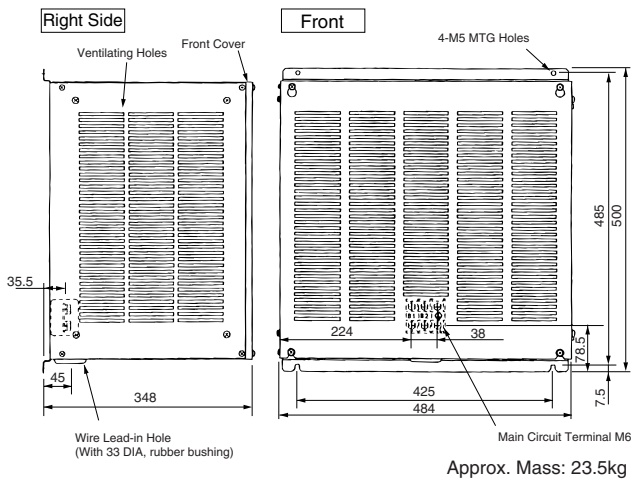
Type: JUSP-RA14 (for 37kW)



Type: JUSP-RA15 for 45kW



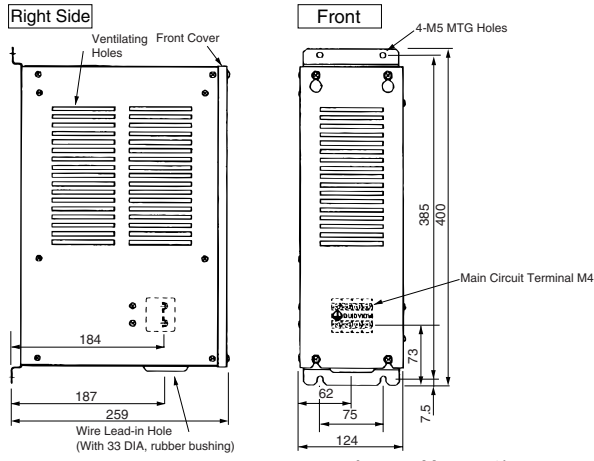
Type: JUSP-RA16 (for 55kW)



AC Servo Systems

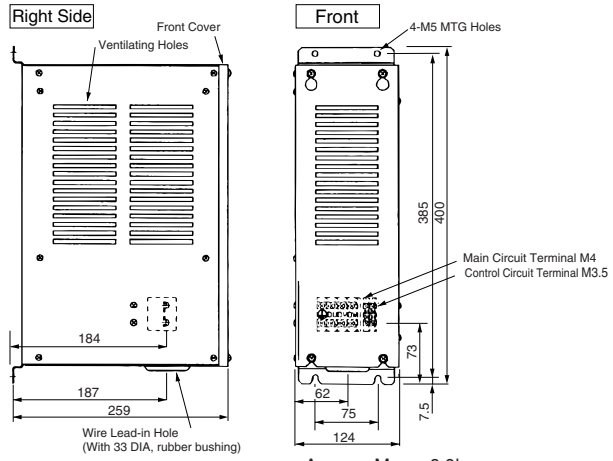
DB Resistor Unit

Type: JUSP-DB03 (for 22/30kW)



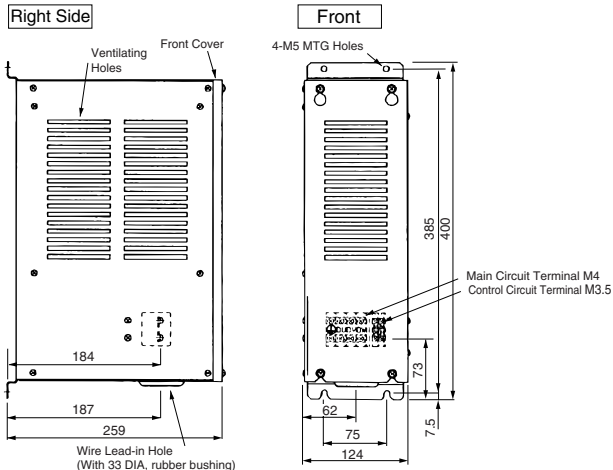
Approx. Mass: 5.0kg

Type: JUSP-DB04 (for 37kW)



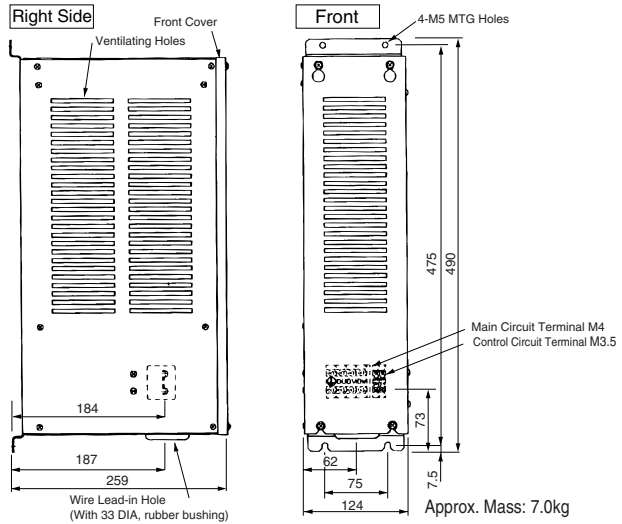
Approx. Mass: 6.0kg

Type: JUSP-DB05 (for 45kW)



Approx. Mass: 6.0kg

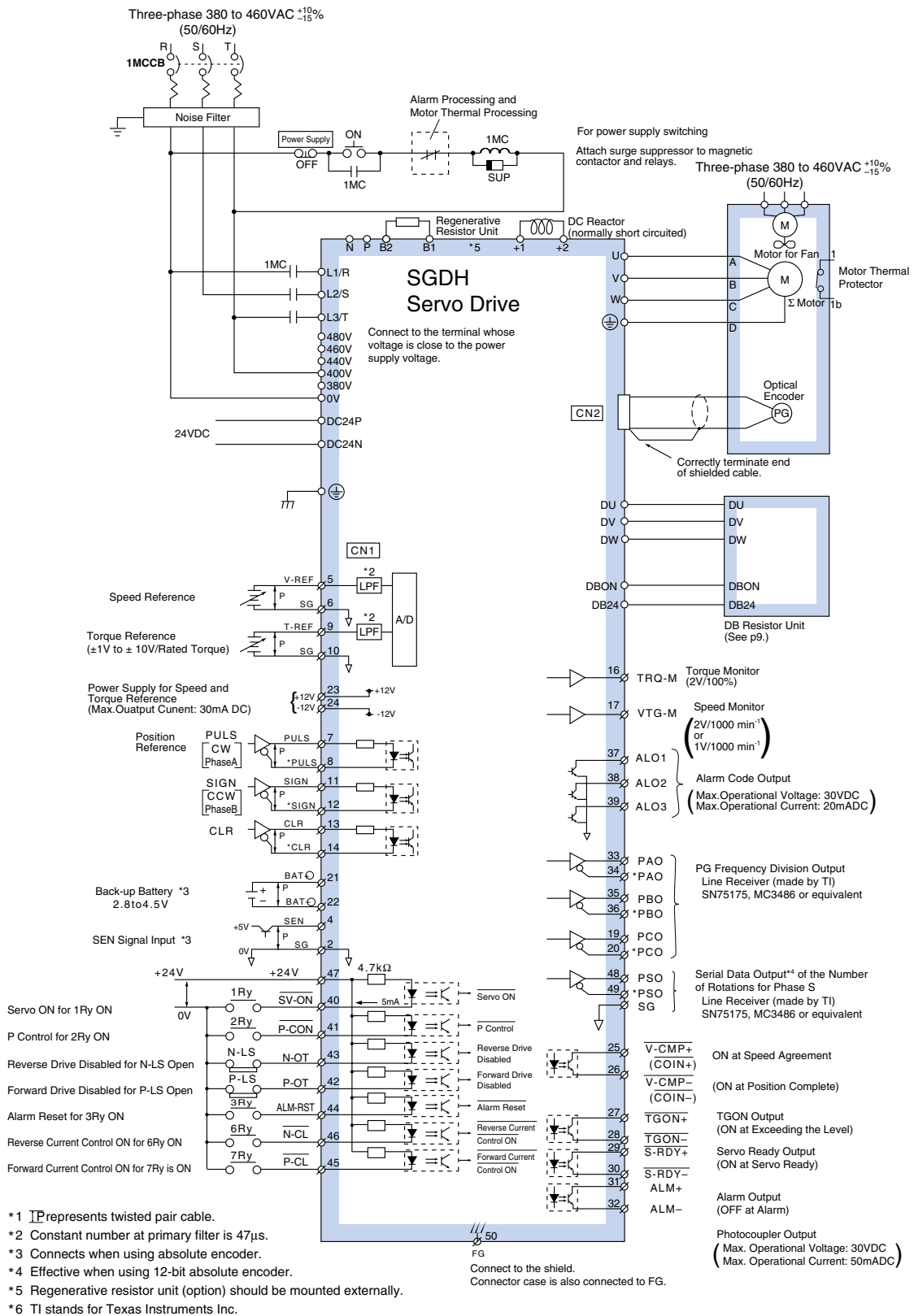
Type: JUSP-DB06 (for 55kW)



Approx. Mass: 7.0kg

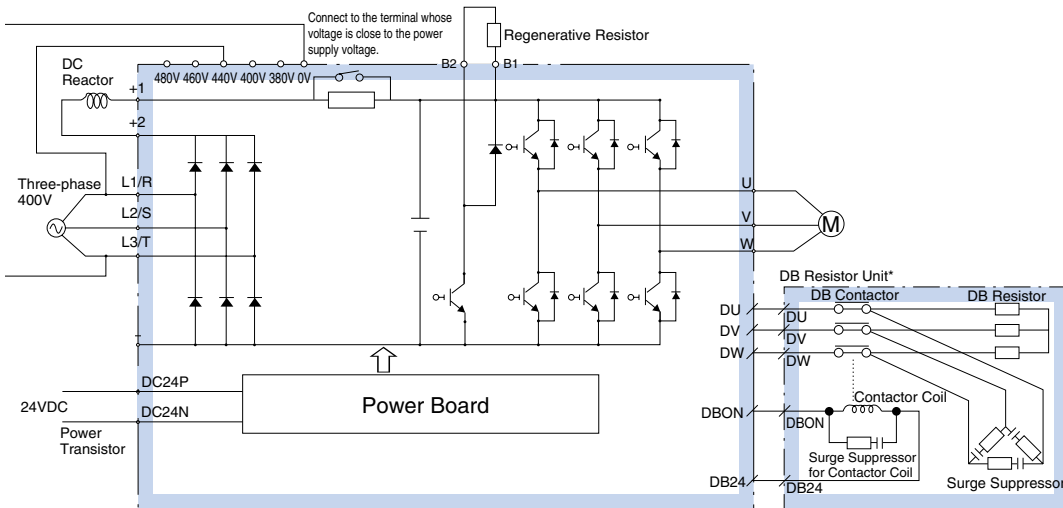
Installation

Standard Connections



AC Servo Systems

Main Circuit Connection



* This diagram is an example of a DB resistor unit with a built-in DB contactor and a surge suppressor for 37 to 55kW. A unit for 22/30kW consists of the resistor only.

Main Circuit Terminal Description

Terminal Symbol	Name	Description	Terminal Symbol	Name	Description
L1/R, L2/S, L3/T	Main Circuit Power Supply Input Terminal	Three-phase 380 to 460 VAC, +10 to -15%, 50/60 Hz	B1, B2	Regenerative Resistor	Connects regenerative resistor
DC24P	Control Power Supply Input Terminal	24VDC	-	Main Circuit Negative Side Terminal	(Normally external connection is not necessary).
DC24N			DU, DV, DW	DB Resistor Unit, DB Contactor Connection Terminal	Connects DB resistor unit or DB contactor.
U, V, W	Motor Connection Terminal	Connect with motor	DBON, DB24	DB Resistor Unit Connection Terminal	For 37 to 55kW, connects to DBON and DB24 terminals or DB resistor unit.
≡ (X2)	Earth Terminal	Grounded (for power supply earth and motor earth).	480V, 460V, 440 V, 400 V, 380 V, 0V	Control Power Supply Input Terminal	Connect to the terminal whose voltage is close to the power supply voltage.
+1, +2	DC Reactor Connection Terminal	Connect DC reactor for suppressing high-harmonic wave. If not necessary, shorten the terminals.			

Control Circuit Terminal Description

CN1 (Connector I/O) Terminal Layout

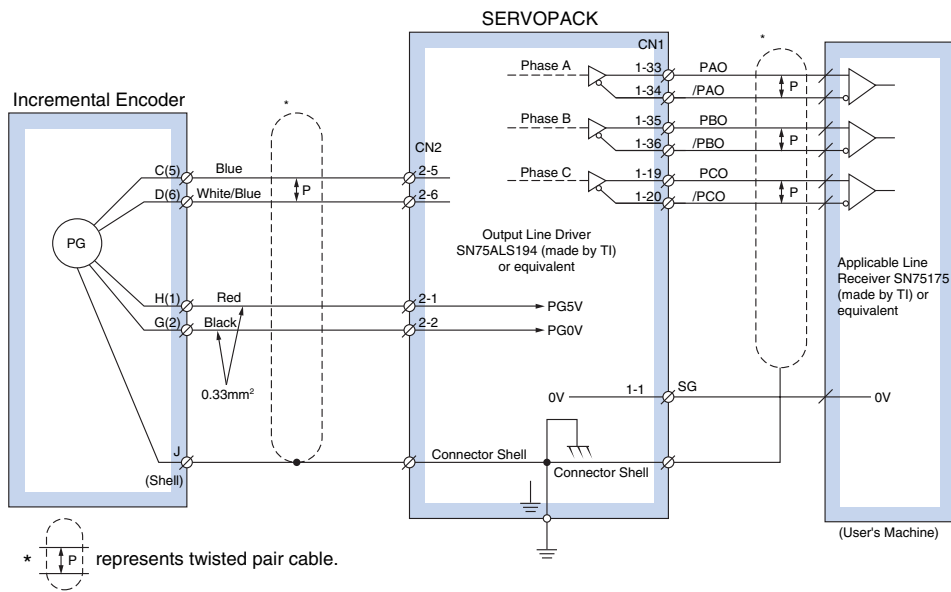
1	SG	GND	27	/TGON+	TGON output signal	26	/V-CMP (COIN-)	Speed agreement signal output
2	SG	GND	28	/S-RDY+	Servo ready output	28	/TGON-	TGON output signal
3	PL1	Power supply for open collector ref.	29	/S-RDY-	Servo ready output	30	/S-RDY-	Servo ready output
4	SEN	SEN signal input	31	ALM+	Servo alarm output	32	ALM-	Servo alarm output
5	V-REF	Speed ref. input	33	PAO	PG dividing output phase A	34	/PAO	PG dividing output phase A
6	SG	GND	35	PBO	PG dividing output phase B	36	/PBO	PG dividing output phase B
7	PULS	Ref. pulse input	37	ALO1	Alarm code output	38	ALO2	Alarm code output
8	/PULS	Ref. pulse input	39	ALO3	(Open collector)	40	/S-ON	Servo ON input
9	T-REF	Torque ref. input	41	/P-CON	P control input	42	P-OT	Fwd. overtravel input
10	SG	GND	43	N-OT	Rev. side overtravel input	44	/ALM-RST	Alarm reset input
11	SIGN	Ref. code input	45	/P-CL	Fwd. current limit ON input	46	/N-CL	Rev. current limit ON input
12	/SIGN	Ref. code input	47	+24V IN	External input power supply	48	PSO	Phase S signal output
13	PL2	Power supply for open collector ref.	49	/PSO	Phase S signal output	50	-	-
14	/CLR	Clear input						
15	CLR	Clear input						
16	-	-						
17	-	-						
18	PL3	Power supply for open collector ref.						
19	PCO	PG dividing output phase C						
20	/PCO	PG dividing output phase C						
21	BAT (+)	Battery (+)						
22	BAT (-)	Battery (-)						
23	-	-						
24	-	-						
25	/V-CMP (COIN+)	Speed agreement signal output						

CN2 (Encoder Connection) Terminal Layout

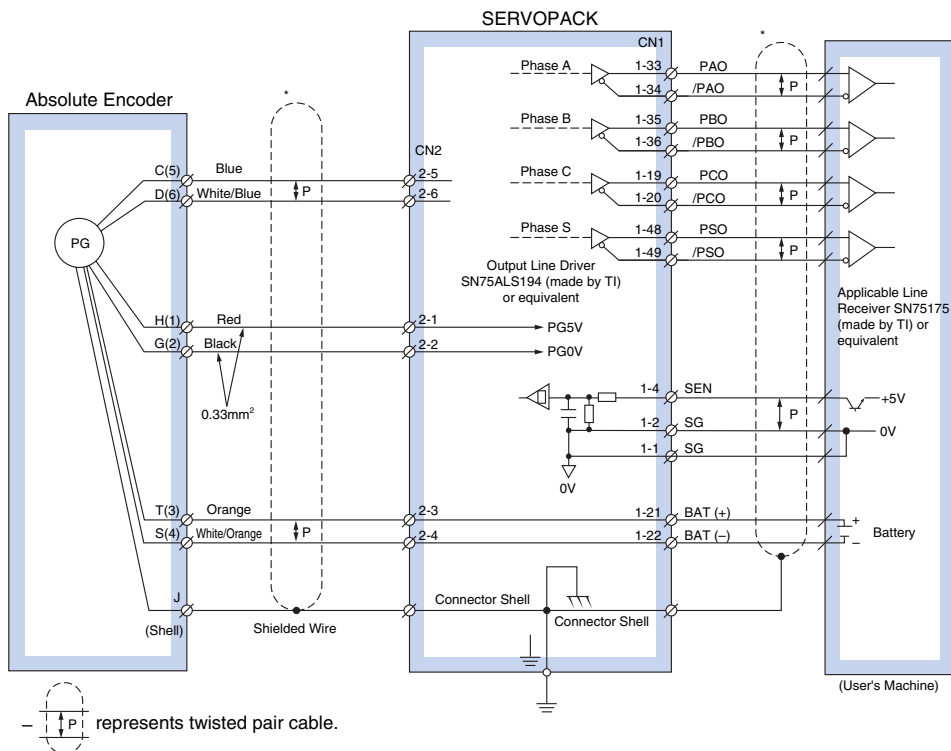
1	PG5V	PG power supply+5V	2	PG 0V	PG power supply 0V
3	BAT(+)	Battery(+) (absolute encoder only)	4	BAT(-)	Battery(-) (absolute encoder only)
5	PS	PG serial signal input	6	/PS	PG serial signal input

Encoder Connections

Incremental Encoder



Absolute Encoder



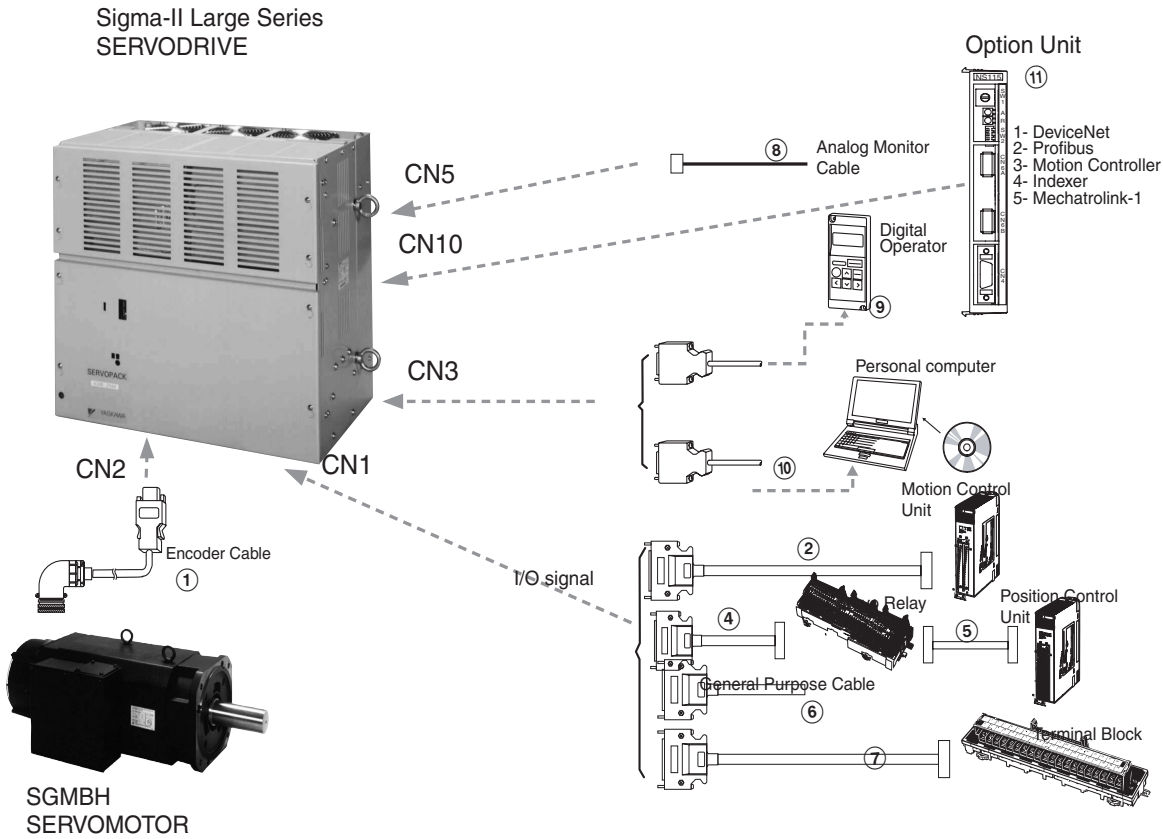
System Configuration Example

Large-capacity AC servo drive configurations are illustrated below.
Connectors and operators are not provided with servomotors and Servo Drives.
Order what you need separately.

AC Servo Systems

Ordering Information

System Configuration



Servomotors

SGMBH - Servomotors 1500 r/min (22 - 55 kW)



Servo Drives

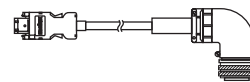
SGDH - Servo Drives (22 - 55 kW)



Specifications				Model
Incremental Encoder (17 bit) Straight shaft with key & Tap	Without brake Flange Mount	140 Nm	22 kW	SGMBH-2BDCA61
		191 Nm	30 kW	SGMBH-3ZDCA61
		236 Nm	37 kW	SGMBH-3GDCA61
		286 Nm	45 kW	SGMBH-4EDCA61
	Without brake Foot mount	236 Nm	37 kW	SGMBH-3GDCA1
		286 Nm	45 kW	SGMBH-4EDCA1
		350 Nm	55 kW	SGMBH-5EDCA1
		140 Nm	22 kW	SGMBH-2BDCA6C
	With brake Flange Mount	191 Nm	30 kW	SGMBH-3ZDCA6C
		236 Nm	37 kW	SGMBH-3GDCA6C
		286 Nm	45 kW	SGMBH-4EDCA6C
		236 Nm	37 kW	SGMBH-3GDCA1C
With brake Foot mount	286 Nm	45 kW	SGMBH-4EDCA1C	
	140 Nm	22 kW	SGMBH-2BD2A61	
	191 Nm	30 kW	SGMBH-3ZD2A61	
	236 Nm	37 kW	SGMBH-3GD2A61	
Absolute Encoder (17 bit) Straight shaft with key & Tap	Without brake Flange Mount	286 Nm	45 kW	SGMBH-4ED2A61
		236 Nm	37 kW	SGMBH-3GD2A1
		286 Nm	45 kW	SGMBH-4ED2A1
		350 Nm	55 kW	SGMBH-5ED2A1
	Without brake Foot mount	236 Nm	37 kW	SGMBH-3GD2A1
		286 Nm	45 kW	SGMBH-4ED2A1
		350 Nm	55 kW	SGMBH-5ED2A1
		140 Nm	22 kW	SGMBH-2BD2A6C
	With brake Flange Mount	191 Nm	30 kW	SGMBH-3ZD2A6C
		236 Nm	37 kW	SGMBH-3GD2A6C
		286 Nm	45 kW	SGMBH-4ED2A6C
		236 Nm	37 kW	SGMBH-3GD2A1C
With brake Foot mount	286 Nm	45 kW	SGMBH-4ED2A1C	
	236 Nm	37 kW	SGMBH-3GD2ALC	
	286 Nm	45 kW	SGMBH-4ED2ALC	
	286 Nm	45 kW	SGMBH-4ED2ALC	

Specifications	Model	Compatible Servomotors	
3 Phase 400 V AC	22.0 kW	SGDH-2BDE	SGMBH-2BD□
	30.0 kW	SGDH-3ZDE	SGMBH-3ZD□
	37.0 kW	SGDH-3GDE	SGMBH-3GD□
	45.0 kW	SGDH-4EDE	SGMBH-4ED□
	55.0 kW	SGDH-5EDE	SGMBH-5ED□

Encoder Cables (for CN2)



Symbol	Specifications	Model	
(1)	Encoder cable (for motors SGMBH-□)	3 m	R88A-CRWB003N-E
		5 m	R88A-CRWB005N-E
		10 m	R88A-CRWB010N-E
		15 m	R88A-CRWB015N-E
		20 m	R88A-CRWB020N-E

Control Cables (for CN1)

Symbol	Description	Connect to	Model		
②	Control Cable (1 Axis)	Motion Control Units CS1W-MC221	1 m R88A-CPW001M1		
		CS1W-MC421	2 m R88A-CPW002M1		
		C200H-MC221	3 m R88A-CPW003M1		
			5 m R88A-CPW005M1		
	Control Cable (2 Axis)	Motion Control Units CS1W-MC221	1 m R88A-CPW001M2		
		CS1W-MC421	2 m R88A-CPW002M2		
		C200H-MC221	3 m R88A-CPW003M2		
			5 m R88A-CPW005M2		
	Terminal Block (4 Axes)	Motion Control Unit C200HW-MC402-E	- R88A-TC04-E		
	Servodrive connecting Cable (1 Axis)		1 M R88A-CMUK001J3-E2		
	PLC Unit Control Cables (4 Axes)		1 m R88A-CMX001S-E		
			1 m R88A-CMX001J1-E		
	③	Servo Relay Unit	CS1W-NC1□3, CJ1W-NC1□3, or C200HW-NC113 Position Control Unit	XW2B-20J6-1B (1 axis)	
CS1W-NC2□3/4□3, CJ1W-NC2□3/4□3, or C200HW-NC213/413 Position Control Unit			XW2B-40J6-2B (2 axes)		
CQM1H-PLB21			XW2B-20J6-3B (1 axis)		
CQM1-CPU43			XW2B-20J6-8A (1 axis)		
CJ1M-CPU22/23			XW2B-40J6-9A (2 axes)		
Cable to Servo drive		Servo Relay Units XW2B-□0J6-□B	1 m XW2Z-100J-B4		
			2 m XW2Z-200J-B4		
		⑤	Position Control Unit Connecting Cable	C200H-NC112	0.5 m XW2Z-050J-A1
					1 m XW2Z-100J-A1
				C200H-NC211	0.5 m XW2Z-050J-A2
	1 m XW2Z-100J-A2				
CQM1-CPU43-V1 and CQM1H-PLB21	0.5 m XW2Z-050J-A3				
	1 m XW2Z-100J-A3				
CS1W-NC113 and C200HW-NC113	0.5 m XW2Z-050J-A6				
	1 m XW2Z-100J-A6				
CS1W-NC213/413 and C200HW-NC213/413	0.5 m XW2Z-050J-A7				
	1 m XW2Z-100J-A7				
⑥	Control Cable	CS1W-NC133	0.5 m XW2Z-050J-A10		
			1 m XW2Z-100J-A10		
		CS1W-NC233/433	0.5 m XW2Z-050J-A11		
			1 m XW2Z-100J-A11		
		CJ1W-NC113	0.5 m XW2Z-050J-A14		
			1 m XW2Z-100J-A14		
		CJ1W-NC213/413	0.5 m XW2Z-050J-A15		
			1 m XW2Z-100J-A15		
		CJ1W-NC133	0.5 m XW2Z-050J-A18		
			1 m XW2Z-100J-A18		
⑦	Relay Terminal Block Cable	General-purpose Controller	1 m R88A-CTW001N		
			2 m R88A-CTW002N		
	Relay Terminal Block		- XW2B-50G5		

Battery Backup for absolute encoder

Name	Model
Battery (Required for servomotors with absolute encoder)	JZSP-BA01 or ER6VC3 (3.6V)

Cable (for CN5)

Symbol	Name	Model
⑧	Analog Monitor Cable	R88A-CMW001S or DE9404559

Options (for CN3)

Symbol	Name	Model
⑨	Parameter Unit with Cable	JUSP-OP02A-2 or R88A-PR02W
⑩	Computer Connecting Cable	R88A-CCW002P2 or JZSP-CMS02

Option Units (for CN10)

Symbol	Name	Model
⑪	1.5 axis Advanced Motion Controller with Host Link Interface	R88A-MCW151-E
	1.5 axis Advanced Motion Controller with DeviceNet Interface	R88A-MCW151-DRT-E
	Mechatrolink-I Interface unit	JUSP-NS100
	DeviceNet Interface unit with Positioning Functionality	JUSP-NS300
	PROFIBUS-DP Interface unit with Positioning Functionality	JUSP-NS500
	Indexer Unit. Versatile Point to Point Positioning	JUSP-NS600

Connectors

Specification	Model
Control I/O connector (For CN1)	R88A-CNU11C or JZSP-CKI9
Sigma-II Drive Encoder connector (For CN2)	JZSP-CMP9-1
Military Connector for Encoder, IP67 (For Motors SGMBH-□)	MS3108E20-29S
Military Connector for Fan, IP67 (For Motors SGMBH-□)	MS3108E18-10S

Filters

Specifications (applicable Servo Drive)	Model	Rated Current
SGDH-2BDE, SGDH-3ZDE, SGDH-3GDE	FN258-180-07	180 A
SGDH-4EDE, SGDH-5EDE	FN359-250-99	250 A

Regenerative Resistor Units

Servo Drive Model	Regenerative Resistor Unit Model	Specifications
SGDH-2BDE	JUSP-RA12	9Ω, 3600 W
SGDH-3ZDE	JUSP-RA13	6.7Ω, 3600 W
SGDH-3GDE	JUSP-RA14	5Ω, 4800 W
SGDH-4EDE	JUSP-RA15	4Ω, 6000 W
SGDH-5EDE	JUSP-RA16	3.8Ω, 7200 W

DB Resistor units

Servo Drive Model	Regenerative Resistor Unit Model	Specifications. Star Wiring
SGDH-2BDE, SGDH-3ZDE	JUSP-DB03	180 W, 0.8Ω
SGDH-3GDE	JUSP-DB04	180 W, 0.8Ω
SGDH-4EDE	JUSP-DB05	180 W, 0.8Ω
SGDH-5EDE	JUSP-DB06	300 W, 0.8Ω

Computer Software

Specifications	Model
SigmaWin	MOTION TOOLS CD

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.

To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.