

Rotary Pulse Indicator K3HB-R

CSM_K3HB-R_DS_E_6_1


Digital Rotary Pulse Meter Capable of 50 kHz Measurements

- Measures High-speed Pulses at 50 kHz.
Provides high-speed pulse measurements up to 50 kHz of rotary encoder or ON/OFF pulse signals and can perform rotating measurement of high-speed rotating objects.

Note: No-voltage contacts of up to 30 Hz are supported.

- Six Measurement Operations Including Rotation (rpm)/Circumferential Speed, Ratio, and Cumulative
One Rotary Pulse Meter has 6 rotary pulse measurement functions to support a variety of pulse measurement applications. Select the best function for your application from the following: Rotation (rpm)/circumferential speed/instantaneous flowrate (value proportional to frequency), absolute ratio, error ratio, error, flow rate ratio, and passing speed (value inversely proportional to frequency).



 Refer to *Safety Precautions for All Digital Panel Meters*.

Model Number Structure

Model Number Legend

Base Units and Optional Boards can be ordered individually or as sets.

Base Units

K3HB-R
1 5

1. Input Sensor Code

NB: NPN input/voltage pulse input
PB: PNP input

5. Supply Voltage

100-240 VAC: 100 to 240 VAC
24 VAC/VDC: 24 VAC/VDC

Optional Boards

Sensor Power Supply/Output Boards

K33-
2

Relay/Transistor Output Boards

K34-
3

Event Input Boards

K35-
4

Base Units with Optional Boards

K3HB-R-
1 2 3 4 5

2. Sensor Power Supply/Output Type Code

- None: None
- CPA: Relay output (PASS: SPDT) + Sensor power supply (12 VDC±10%, 80 mA) (See note 1.)
- L1A: Linear current output (0 to 20 or 4 to 20 mA DC) + Sensor power supply (12 VDC±10%, 80 mA) (See note 2.)
- L2A: Linear voltage output (0 to 5, 1 to 5, or 0 to 10 VDC) + Sensor power supply (12 VDC±10%, 80 mA) (See note 2.)
- A: Sensor power supply (12 VDC ±10%, 80 mA)
- FLK1A: Communications (RS-232C) + Sensor power supply (12 VDC±10%, 80 mA) (See note 2.)
- FLK3A: Communications (RS-485) + Sensor power supply (12 VDC±10%, 80 mA) (See note 2.)

3. Relay/Transistor Output Type Code

- None: None
 - C1: Relay contact (H/L: SPDT each)
 - C2: Relay contact (HH/H/LL/L: SPST-NO each)
 - T1: Transistor (NPN open collector: HH/H/PASS/L/LL)
 - T2: Transistor (PNP open collector: HH/H/PASS/L/LL)
 - BCD*: BCD output + transistor output (NPN open collector: HH/H/PASS/L/LL)
 - DRT: DeviceNet (See note 2.)
- * A Special BCD Output Cable (sold separately) is required.

4. Event Input Type Code

- None: None
- 1: 5 inputs (M3 terminal blocks), NPN open collector
- 2: 8 inputs (10-pin MIL connector), NPN open collector
- 3: 5 inputs (M3 terminal blocks), PNP open collector
- 4: 8 inputs (10-pin MIL connector), PNP open collector

Note: 1. CPA can be combined with relay outputs only.

2. Only one of the following can be used by each Digital Indicator: RS-232C/RS-485 communications, BCD communications, or DeviceNet communications.

Accessories (Sold Separately)

K32-DICN: Special Cable (for event inputs with 8-pin connector)

K32-BCD: Special BCD Output Cable

Rubber Packing

Model
K32-P1

Note: Rubber packing is provided with the Controller.

Specifications

■ Ratings

Supply voltage	100 to 240 VAC, 24 VAC/VDC, DeviceNet power supply: 24 VDC	
Allowable power supply voltage range	85% to 110% of the rated power supply voltage, DeviceNet power supply: 11 to 25 VDC	
Power consumption (See note 1.)	100 to 240 VAC: 18 VA max. (max. load) 24 VAC/DC: 11 VA/7 W max. (max. load)	
Current consumption	DeviceNet power supply: 50 mA max. (24 VDC)	
Input	No-voltage contact, voltage pulse, open collector	
External power supply	12 VDC \pm 10%, 80 mA (models with external power supply only)	
Event inputs (See note 2.)	Startup compensation timer input	NPN open collector or no-voltage contact signal ON residual voltage: 2 V max.
	Hold input	ON current at 0 Ω : 4 mA max.
	Reset input	Max. applied voltage: 30 VDC max.
	Bank input	OFF leakage current: 0.1 mA max.
Output ratings (depends on the model)	Relay output	250 VAC, 30 VDC, 5 A (resistive load) Mechanical life expectancy: 5,000,000 operations, Electrical life expectancy: 100,000 operations
	Transistor output	Maximum load voltage: 24 VDC, Maximum load current: 50 mA, Leakage current: 100 μ A max.
	Linear output	Linear output 0 to 20 mA DC, 4 to 20 mA DC: Load: 500 Ω max, Resolution: Approx. 10,000, Output error: \pm 0.5% FS Linear output 0 to 5 VDC, 1 to 5 VDC, 0 to 10 VDC: Load: 5 k Ω max, Resolution: Approx. 10,000, Output error: \pm 0.5% FS (1 V or less: \pm 0.15 V; no output for 0 V or less)
Display method	Negative LCD (backlit LED) display 7-segment digital display (Character height: PV: 14.2 mm (green/red); SV: 4.9 mm (green))	
Main functions	Scaling function, measurement operation selection, averaging, output hysteresis, output OFF delay, output test, teaching, display value selection, display color selection, key protection, bank selection, display refresh period, maximum/minimum hold, reset	
Ambient operating temperature	-10 to 55°C (with no icing or condensation)	
Ambient operating humidity	25% to 85%	
Storage temperature	-25 to 65°C (with no icing or condensation)	
Altitude	2,000 m max.	
Accessories	Watertight packing, 2 fixtures, terminal cover, unit stickers, instruction manual. DeviceNet models also include a DeviceNet connector (Hirose HR31-5.08P-5SC(01)) and crimp terminals (Hirose HR31-SC-121) (See note 3.)	

- Note:**
1. DC power supply models require a control power supply capacity of approximately 1 A per Unit when power is turned ON. Particular attention is required when using two or more DC power supply models. The OMRON S8VS-series DC Power Supply Unit is recommended.
 2. PNP input types are also available.
 3. For K3HB-series DeviceNet models, use only the DeviceNet Connector included with the product. The crimp terminals provided are for Thin Cables.

■ Characteristics

Display range	-19,999 to 99,999	
Measurement accuracy (at 23±5°C)	Functions F1, F6: ±0.006% rgd ±1 digit (for voltage pulse/open collector sensors) Functions F2 to F5: ±0.02% rgd ±1 digit (for voltage pulse/open collector sensors)	
Measurement range	Functions F1 to F6: 0.5 mHz to 50 kHz (for voltage pulse/open collector sensors)	
Input signals	Contact input (dry contact input) (30-Hz max. with ON/OFF pulse width of 15 ms min.) No contact voltage pulse (50-KHz max. with ON/OFF pulse width of 9 µs min.; ON voltage: 4.5 to 30 V; OFF voltage: -30 to 2 V; input impedance: 10 kΩ) Open collector (50-KHz max. with ON/OFF pulse width of 9 µs min.)	
Connectable sensors	ON residual voltage: 3 V max. OFF leakage current: 1.5 mA max. Load current: Must have a switching capacity of 20 mA or higher. Must be able to properly switch load currents of 5 mA or less.	
Comparative output response time (transistor output)	Functions F1 to F6: 100 ms max. (time until the comparative output is made when there is a forced sudden change in the input signal from 15% to 95% or 95% to 15%.)	
Linear output response time	Functions F1 to F6: 110 ms max. (time until the final analog output value is reached when there is a forced sudden change in the input signal from 15% to 95% or 95% to 15%.)	
Insulation resistance	20 MΩ min. (at 500 VDC)	
Dielectric strength	2,300 VAC for 1 min between external terminals and case	
Noise immunity	100 to 240 VAC models: ±1,500 V at power supply terminals in normal or common mode (waveform with 1-ns rising edge and pulse width of 1 µs/100 ns) 24 VAC/VDC models: ±1,500 V at power supply terminals in normal or common mode (waveform with 1-ns rising edge and pulse width of 1 µs/100 ns)	
Vibration resistance	Frequency: 10 to 55 Hz; Acceleration: 50 m/s ² , 10 sweeps of 5 min each in X, Y, and Z directions	
Shock resistance	150 m/s ² (100 m/s ² for relay outputs) 3 times each in 3 axes, 6 directions	
Weight	Approx. 300 g (Base Unit only)	
Degree of protection	Front panel	Conforms to NEMA 4X for indoor use (equivalent to IP66)
	Rear case	IP20
	Terminals	IP00 + finger protection (VDE0106/100)
Memory protection	EEPROM (non-volatile memory) Number of rewrites: 100,000	
Applicable standards	UL61010C-1, CSA C22.2 No. 1010.1 (evaluated by UL) EN61010-1 (IEC61010-1): Pollution degree 2/Overvoltage category II EN61326: 1997, A1: 1998, A2: 2001	
EMC	EMI: EN61326 industrial applications Electromagnetic radiation interference CISPR 11 Group 1, Class A Terminal interference voltage CISPR 11 Group 1, Class A EMS: EN61326 industrial applications Electrostatic Discharge Immunity EN61000-4-2: 4 kV (contact), 8 kV (in air) Radiated Electromagnetic Field Immunity EN61000-4-3: 10 V/m 1 kHz sine wave amplitude modulation (80 MHz to 1 GHz, 1.4 to 2 GHz) Electrical Fast Transient/Burst Noise Immunity EN61000-4-4: 2 kV (power line), 1 kV (I/O signal line) Surge Immunity EN61000-4-5: 1 kV with line (power line), 2 kV with ground (power line) Conducted Disturbance Immunity EN61000-4-6: 3 V (0.15 to 80 MHz) Power Frequency Magnetic Immunity EN61000-4-8: 30 A/m (50 Hz) continuous time Voltage Dips and Interruptions Immunity EN61000-4-11: 0.5 cycle, 0°/180°, 100% (rated voltage)	

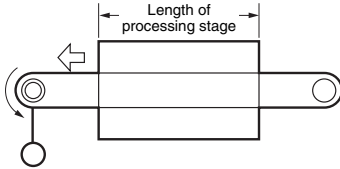
Operation

■ Functions (Operating Modes)

F1 to F6

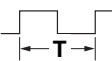
Functions F1 to F6 provide rpm/circumferential speed and other calculation displays by measuring continuous pulses (frequencies).

Example



- F1: Displays rotation (rpm) or circumferential speed for one input.
- F2 to F5: Displays the calculation result for two rotation (rpm) speeds.
- F6: Displays the passing time calculated from the circumferential speed and the length of the processing stage for one input.

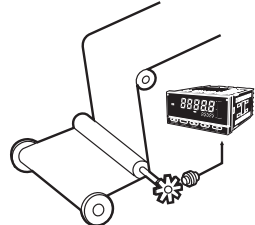
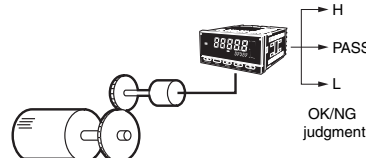
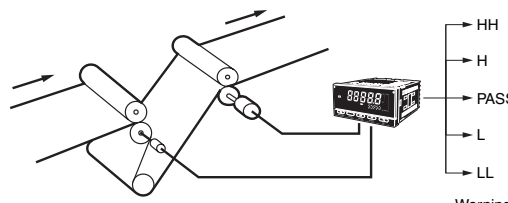
The basic principle used by the Digital Indicator to calculate the rotation speed (rpm) display is to count the ON/OFF time (T) for input sensor or other device inputs using the internal system clock, and then automatically calculate the frequency. This frequency (f) is multiplied by 60 and displayed as the rotation (rpm) speed.

Input sensor or other input pulse ON/OFF time (T) =  Frequency (f) = $\frac{1}{T}$

- Rotation speed (rpm) = $f \times 60$
- Circumferential speed = Roll circumference \times Rotation speed (rpm)
- Passing time = $\frac{\text{Length of processing stage}}{\text{Circumferential speed}}$

These calculations are automatically made internally and displayed whenever any input pulse is received.

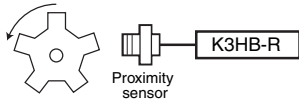
Function name	Function No.
Rpm/circumferential speed	F1
Absolute ratio	F2
Error ratio	F3
Rotational difference	F4
Flow rate ratio	F5
Passing time	F6

Function	Operation	Operation image (application)																										
F1 Rpm/circumferential speed/ Instantaneous flowrate	Measures frequency for input A and displays the rotation (rpm) or circumferential speed proportional to the input frequency. Display value $D = fa \times 60 \times \alpha$ fa: Input frequency (Hz)	Measuring roller winding speed Measuring motor speed (for product testing)  																										
	<table border="1"> <thead> <tr> <th>Calculation</th> <th>Display unit</th> <th>Prescale value (α)</th> </tr> </thead> <tbody> <tr> <td rowspan="2">Rotation speed</td> <td>rpm</td> <td>1/N</td> </tr> <tr> <td>rps</td> <td>1/60 N</td> </tr> <tr> <td rowspan="2">Frequency (of input pulse)</td> <td>Hz</td> <td>1/60</td> </tr> <tr> <td>kHz</td> <td>1/60000</td> </tr> <tr> <td rowspan="5">Circumferential speed</td> <td>mm/s</td> <td>1000 $\pi d/60$ N</td> </tr> <tr> <td>cm/s</td> <td>100 $\pi d/60$ N</td> </tr> <tr> <td>m/s</td> <td>$\pi d/60$ N</td> </tr> <tr> <td>m/min</td> <td>$\pi d/N$</td> </tr> <tr> <td>km/h</td> <td>0.06 $\pi d/N$</td> </tr> <tr> <td rowspan="2">Instantaneous flowrate</td> <td>l/min</td> <td rowspan="2">Check the output specifications of the input device and calculate the prescale value from the following equation: Display value $D = fa \times 60 \times \alpha$</td> </tr> <tr> <td>l/h</td> </tr> </tbody> </table> N = Pulses per rotation πd = Circumferential length per rotation (m)		Calculation	Display unit	Prescale value (α)	Rotation speed	rpm	1/N	rps	1/60 N	Frequency (of input pulse)	Hz	1/60	kHz	1/60000	Circumferential speed	mm/s	1000 $\pi d/60$ N	cm/s	100 $\pi d/60$ N	m/s	$\pi d/60$ N	m/min	$\pi d/N$	km/h	0.06 $\pi d/N$	Instantaneous flowrate	l/min
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Instantaneous flowrate	l/min	Check the output specifications of the input device and calculate the prescale value from the following equation: Display value $D = fa \times 60 \times \alpha$																										
	l/h																											
F2 Absolute ratio	Multiplies input B divided by input A ($\frac{B}{A}$) by 100 and displays the ratio as a percentage (%). Display unit: %	Measuring the speed ratio between two rollers 																										

Function	Operation	Operation image (application)						
F3 Error ratio	<p>Multiplies the error between input A and input B $(\frac{B}{A} - 1)$ by 100 and displays the ratio as a percentage (%).</p> <p>Display unit: %</p>	<p>Measuring the line speed error ratio between two conveyors</p>						
F4 Rotational difference	<p>Displays the difference between input A and input B $(B - A)$ as the rotation (rpm) speed error or circumferential speed error.</p> <p>Display unit: rpm, rps, rph, Hz, kHz, mm/s, m/s m/min, km/h l/min, l/h, etc.</p>	<p>Measuring the rotation (rpm)/circumferential speed error (absolute error) between two conveyors</p>						
F5 Flow rate ratio	<p>Displays the flow rate ratio of B from inputs A and B $(\frac{B}{A+B})$ as a ratio (%).</p> <p>Display unit: %</p>	<p>Monitoring liquid mixture flow rate ratio</p>						
F6 Passing time	<p>The passing time for the desired distance is displayed by measuring the frequency of input A.</p> <p>Passing time (s) = $1/f_a \times \alpha$</p> <p>f_a: Input frequency (Hz)</p> <p>Set the prescale value for the desired display unit using the following table for reference.</p> <table border="1"> <thead> <tr> <th>Calculation</th> <th>Display unit</th> <th>Prescale value (α)</th> </tr> </thead> <tbody> <tr> <td>Passing time</td> <td>s</td> <td>$L/(\pi d/N)$</td> </tr> </tbody> </table> <p>N = Pulses per rotation πd = Circumferential length per rotation (m) L = Length of process (m)</p> <p>Display unit: Seconds (s), minutes (min), hours/minutes/seconds (h.min.s), minutes/seconds/tenths of seconds (min.s.1/10s), etc.</p>	Calculation	Display unit	Prescale value (α)	Passing time	s	$L/(\pi d/N)$	<p>Displaying the passing time for a conveyor line</p>
Calculation	Display unit	Prescale value (α)						
Passing time	s	$L/(\pi d/N)$						

■ What Is Prescaling?

To make calculations using the input pulse to display rotation (rpm) or circumferential speed, the number of pulses per rotation or the length of the circumference must be multiplied by a certain coefficient. This coefficient is called the prescale value.



$$\text{Rotation speed (rpm)} = f \times 60 \times a$$

f: Input pulse frequency (No. of pulses per second)

a: Prescale value

If there are 5 pulses per rotation, then

$$a = 1/5 (= 0.2 = 2 \times 10^{-1})$$

and an accurate rotation speed (rpm) can be calculated.

The actual setting is X = 2.0000 (mantissa) and Y = 10⁻¹ (exponent).

■ What Is the Auto-zero Function?

(Set this function before using the Digital Indicator.)

If a function **F I** to **F 5** is set, the frequency can be force-set to zero if there is no input pulse for a set period. This period is called the auto-zero time. Set the auto-zero time to slightly longer than the longest input pulse interval. (The display will not easily return to zero if the auto-zero time is too long or left at the default setting.)

Time Unit Settings

Setting	Meaning
5 0 R L	Prescale value menu setting
0 0 . 0	Minute display
h . 0 0 . 5 5	h.mm.ss display
0 0 . 5 5 . d	mm.ss.d display (d = tenths of a second)

Note: Time unit can be set only when passing time (F6) is selected.

Input Type Setting

	NO: Voltage pulse high	NC: Voltage pulse low
No-contact or voltage pulse input	0 0	0 1
Contact	1 0	1 1

Note: Set to **1 0** or **1 1** when there is a large variation in the display. The largest measurement range is 30 Hz.

Common Specifications

■ Event Input Ratings

K3HB-R	S-TMR, HOLD, RESET, BANK1, BANK2, BANK4
Contact	ON: 1 k Ω max., OFF: 100 k Ω min.
No-contact	ON residual voltage: 2 V max. OFF leakage current: 0.1 mA max. Load current: 4 mA max. Maximum applied voltage: 30 VDC max.

■ Output Ratings

Contact Output

Item	Resistive loads (250 VAC, $\cos\phi=1$; 30 VDC, L/R=0 ms)	Inductive loads (250 VAC, closed circuit, $\cos\phi=0.4$; 30 VDC, L/R=7 ms)
Rated load	5 A at 250 VAC 5 A at 30 VDC	1 A at 250 VAC 1 A at 30 VDC
Mechanical life expectancy	5,000,000 operations	
Electrical life expectancy	100,000 operations	

Transistor Outputs

Maximum load voltage	24 VDC
Maximum load current	50 mA
Leakage current	100 μ A max.

Linear Output

Item	Outputs	0 to 20 mA	4 to 20 mA	0 to 5 V	1 to 5 V	0 to 10 V
Allowable load impedance		500 Ω max.		5 k Ω min.		
Resolution		Approx. 10,000				
Output error		$\pm 0.5\%$ FS		$\pm 0.5\%$ FS (± 0.15 V for 1 V or less and no output for 0 V)		

Serial Communications Output

Item	Type	RS-232C, RS-485
Communications method		Half duplex
Synchronization method		Start-stop synchronization (asynchronous)
Baud rate		9600/19200/38400 bps
Transmission code		ASCII
Data length		7 bits or 8 bits
Stop bit length		2 bits or 1 bit
Error detection		Vertical parity and FCS
Parity check		Odd, even

BCD Output I/O Ratings

(Input Signal Logic: Negative)

I/O signal name		Item	Rating	
Inputs	REQUEST	Input signal	No-voltage contact input	
	HOLD	Input current for no-voltage input	10 mA	
	MAX	Signal level	ON voltage	1.5 V max.
	MIN		OFF voltage	3 V min.
RESET				
Outputs	DATA	Maximum load voltage	24 VDC	
	POLARITY	Maximum load current	10 mA	
	OVER	Leakage current	100 μ A max.	
	DATA VALID			
	RUN			
HH H PASS L LL		Maximum load voltage	24 VDC	
		Maximum load current	50 mA	
		Leakage current	100 μ A max.	

Refer to the *K3HB Communications User's Manual* (Cat. No. N129) for details on serial and DeviceNet communications.

DeviceNet Communications

Communications protocol		Conforms to DeviceNet																		
Supported communications	Remote I/O communications	Master-Slave connection (polling, bit-strobe, COS, cyclic) Conforms to DeviceNet communications standards.																		
	I/O allocations	Allocate any I/O data using the Configurator. Allocate any data, such as DeviceNet-specific parameters and variable area for Digital Indicators. Input area: 2 blocks, 60 words max. Output area: 1 block, 29 words max. (The first word in the area is always allocated for the Output Execution Enabled Flags.)																		
	Message communications	Explicit message communications CompoWay/F communications commands can be executed (using explicit message communications)																		
Connection methods		Combination of multi-drop and T-branch connections (for trunk and drop lines)																		
Baud rate		DeviceNet: 500, 250, or 125 Kbps (automatic follow-up)																		
Communications media		Special 5-wire cable (2 signal lines, 2 power supply lines, 1 shield line)																		
Communications distance		<table border="1"> <thead> <tr> <th>Baud rate</th> <th>Network length (max.)</th> <th>Drop line length (max.)</th> <th>Total drop line length (max.)</th> </tr> </thead> <tbody> <tr> <td>500 Kbps</td> <td>100 m max. (100 m max.)</td> <td>6 m max.</td> <td>39 m max.</td> </tr> <tr> <td>250 Kbps</td> <td>100 m max. (250 m max.)</td> <td>6 m max.</td> <td>78 m max.</td> </tr> <tr> <td>125 Kbps</td> <td>100 m max. (500 m max.)</td> <td>6 m max.</td> <td>156 m max.</td> </tr> </tbody> </table> <p>The values in parentheses are for Thick Cable.</p>			Baud rate	Network length (max.)	Drop line length (max.)	Total drop line length (max.)	500 Kbps	100 m max. (100 m max.)	6 m max.	39 m max.	250 Kbps	100 m max. (250 m max.)	6 m max.	78 m max.	125 Kbps	100 m max. (500 m max.)	6 m max.	156 m max.
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250 Kbps	100 m max. (250 m max.)	6 m max.	78 m max.																	
125 Kbps	100 m max. (500 m max.)	6 m max.	156 m max.																	
Communications power supply		24-VDC DeviceNet power supply																		
Allowable voltage fluctuation range		11 to 25-VDC DeviceNet power supply																		
Current consumption		50 mA max. (24 VDC)																		
Maximum number of nodes		64 (DeviceNet Configurator is counted as one node when connected.)																		
Maximum number of slaves		63																		
Error control checks		CRC errors																		
DeviceNet power supply		Supplied from DeviceNet communications connector																		

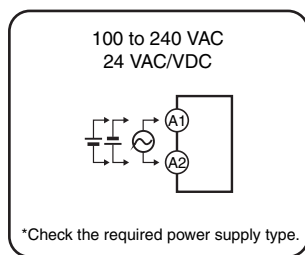
Connections

External Connection Diagrams

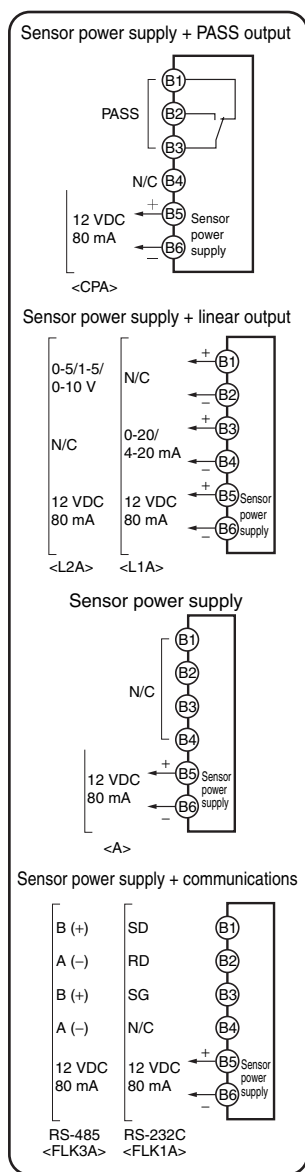
Terminal Arrangements

Note: Refer to *Internal Block Diagram* on page 12 for information on isolation.

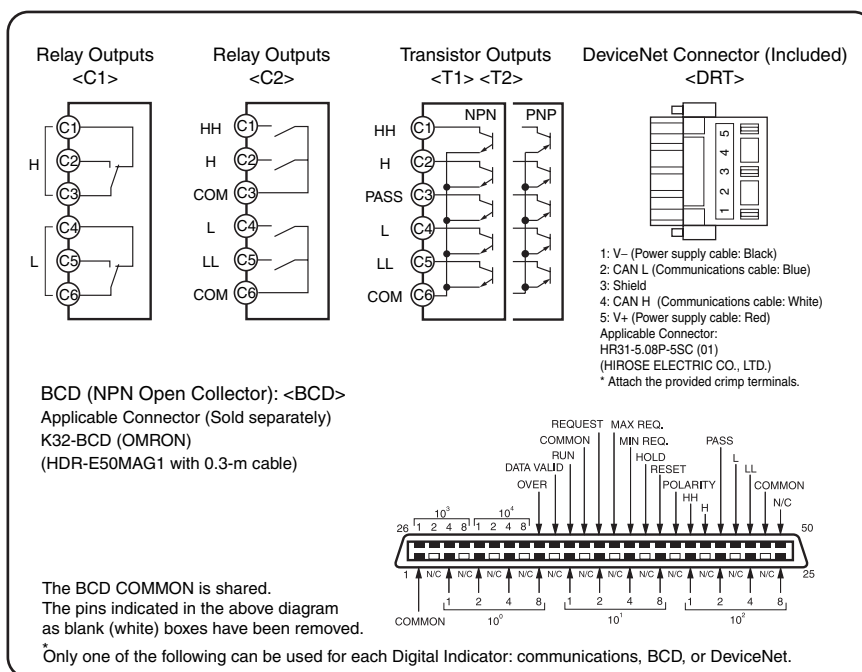
A Operating Power Supply



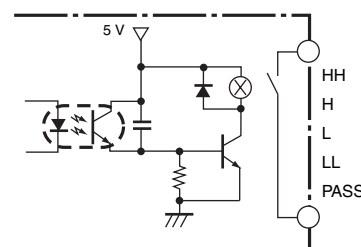
B Sensor Power Supply/Output



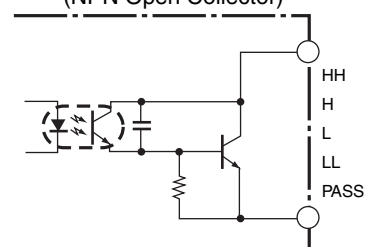
C Relays, Transistors, BCD and DeviceNet



Contact Outputs

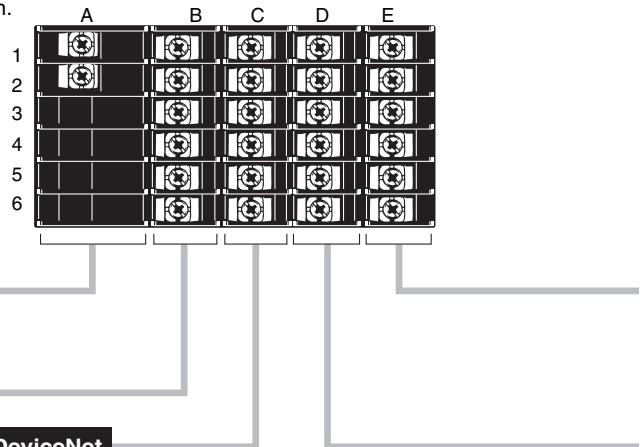


Transistor Outputs (NPN Open Collector)

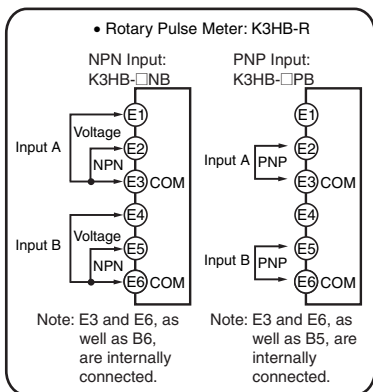


Safety Standards Conformance

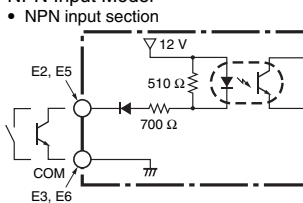
- Always use a EN/IEC-compliant power supply with reinforced insulation or double insulation for the DeviceNet power supply.
- The product must be used indoors for the above applicable standards to apply.



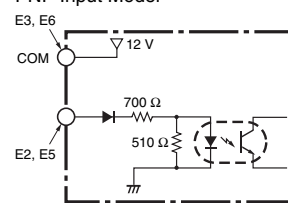
E Pulse Inputs



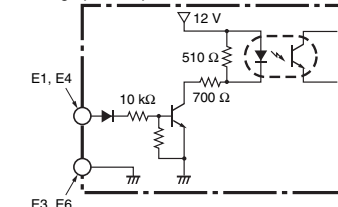
NPN Input Model



PNP Input Model



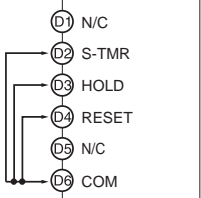
Voltage pulse input section



D Event Inputs

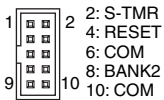
Models with Terminal Blocks

<1> <3>



Models with Connectors

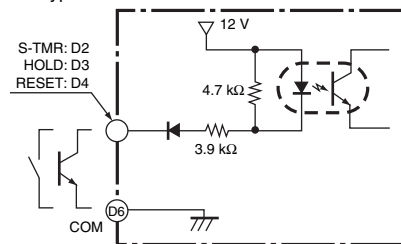
<2> <4>



- Applicable Connector (Sold separately)
XG4M-1030 (OMRON)
- Special Cable (Sold separately)
K32-DICN (OMRON)
(XG4M-1030 with 3-m cable)

- Use terminal pin D6 as the common terminal.
- Use NPN open collector or no-voltage contacts for event input.

PNP types are also available.



BCD Output Cable

Model	Shape	Pin arrangement
K32-BCD	<p>Connected device end (PLC, display device, etc.)</p> <p>Cover: HDR-E50LPA5 (manufactured by Honda Tsushin Co., Ltd.) Connector: HDR-E50MAG1 (manufactured by Honda Tsushin Co., Ltd.)</p> <p>D-sub connector (37-pin female) Cover: 17JE-37H-1A (manufactured by DDK) Connector: Equivalent to 17JE-13370-02 (manufactured by DDK) Stud: 17L-002A (manufactured by DDK)</p>	<p>COMMON</p> <p>10⁰ 2 4 8</p> <p>10¹ 1 2 4 8</p> <p>10² 1 2 4 8</p> <p>10³ 1 2 4 8</p> <p>10⁴ 1 2</p> <p>4 8 10⁴</p> <p>OVER DATA VALID RUN COMMON REQUEST MAX REQ. MIN REQ. HOLD RESET POLARITY HH H PASS L LL COMMON</p>

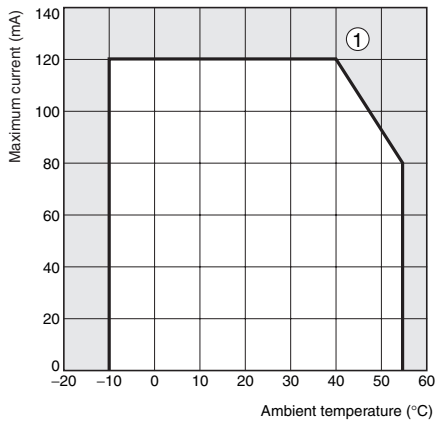
Note: The BCD Output Cable has a D-sub plug. Cover: 17JE-37H-1A (manufactured by DDK); Connector: equivalent to 17JE-23370-02 (D1) (manufactured by DDK)

Special Cable (for Event Inputs with 8-pin Connector)

Model	Appearance	Wiring																						
K32-DICN	<p>3,000 mm Cable marking (3 m)</p>	<table border="1"> <thead> <tr> <th>Pin No.</th> <th>Signal name</th> </tr> </thead> <tbody> <tr><td>1</td><td>N/C</td></tr> <tr><td>2</td><td>S-TMR</td></tr> <tr><td>3</td><td>HOLD</td></tr> <tr><td>4</td><td>RESET</td></tr> <tr><td>5</td><td>N/C</td></tr> <tr><td>6</td><td>COM</td></tr> <tr><td>7</td><td>BANK4</td></tr> <tr><td>8</td><td>BANK2</td></tr> <tr><td>9</td><td>BANK1</td></tr> <tr><td>10</td><td>COM</td></tr> </tbody> </table>	Pin No.	Signal name	1	N/C	2	S-TMR	3	HOLD	4	RESET	5	N/C	6	COM	7	BANK4	8	BANK2	9	BANK1	10	COM
Pin No.	Signal name																							
1	N/C																							
2	S-TMR																							
3	HOLD																							
4	RESET																							
5	N/C																							
6	COM																							
7	BANK4																							
8	BANK2																							
9	BANK1																							
10	COM																							

Derating Curve for Sensor Power Supply (Reference Values)

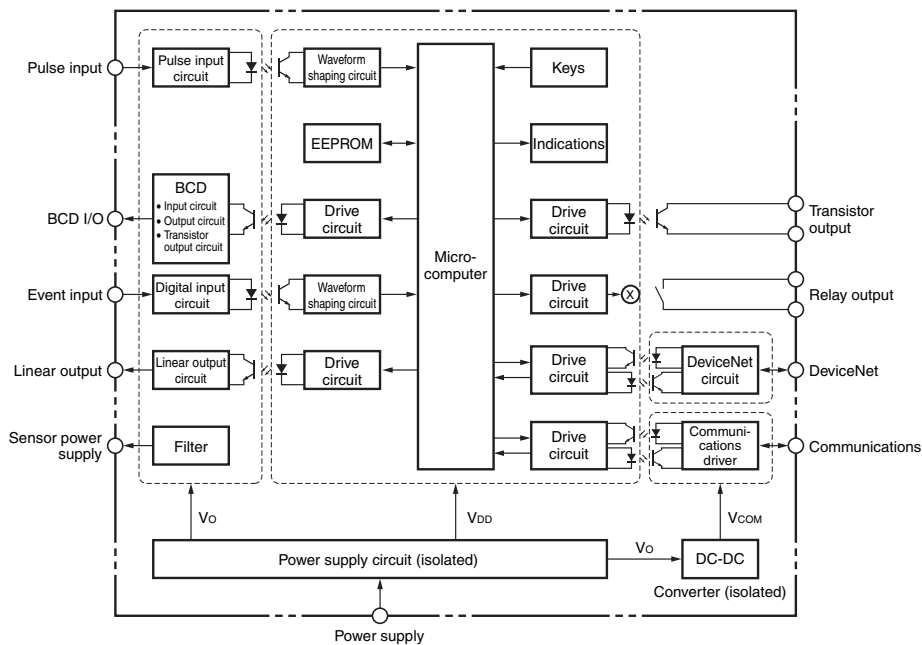
For 12V



Note: 1. The above values were obtained under test conditions with the standard mounting. The derating curve will vary with the mounting conditions, so be sure to adjust accordingly.

2. Internal components may be deteriorated or damaged. Do not use the Digital Indicator outside of the derating range (i.e., do not use it in the area labeled ①, above).

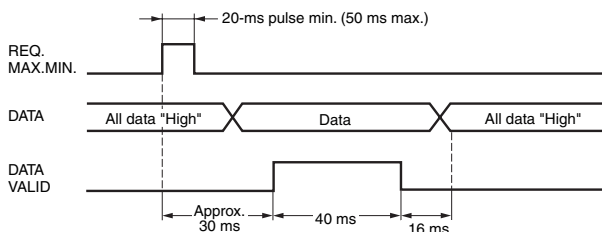
Internal Block Diagram



BCD Output Timing Chart

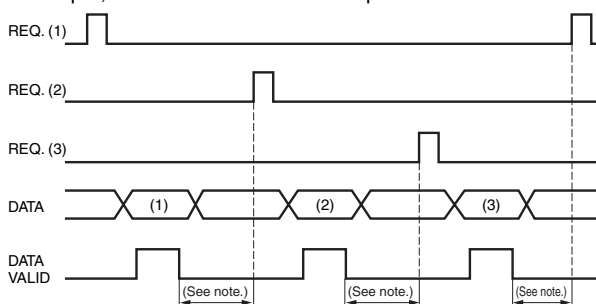
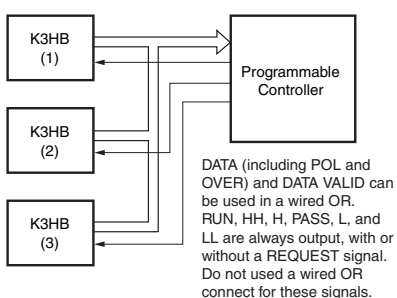
A REQUEST signal from a Programmable Controller or other external device is required to read BCD data.

Single Sampling Data Output



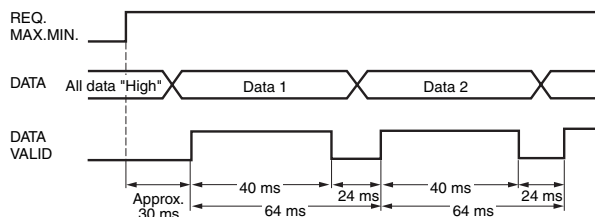
The data is set in approximately 30 ms from the rising edge of the REQUEST signal and the DATA VALID signal is output. When reading the data from a Programmable Controller, start reading the data when the DATA VALID signal turns ON. The DATA VALID signal will turn OFF 40 ms later, and the data will turn OFF 16 ms after that.

- The K3HB BCD output model has an open collector output, so wired OR connection is possible



Note: Leave 20 ms min. between DATA VALID turning OFF and the REQUEST signal.

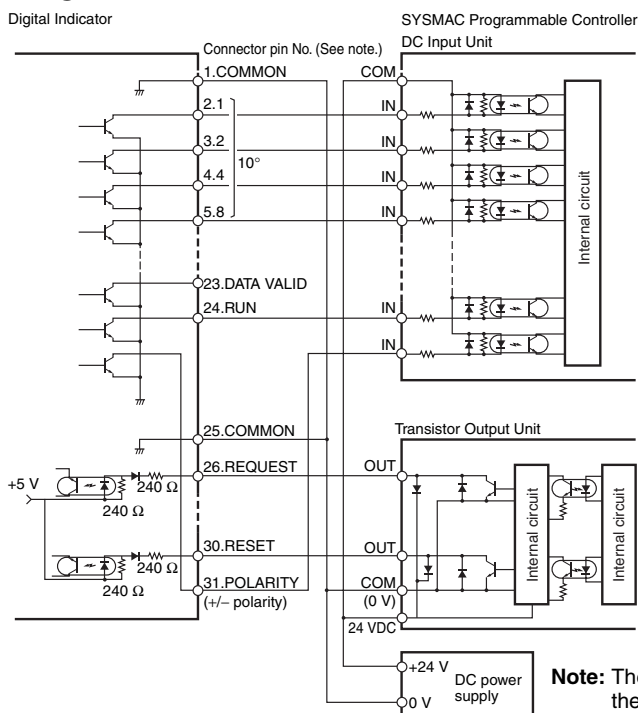
Continuous Data Output



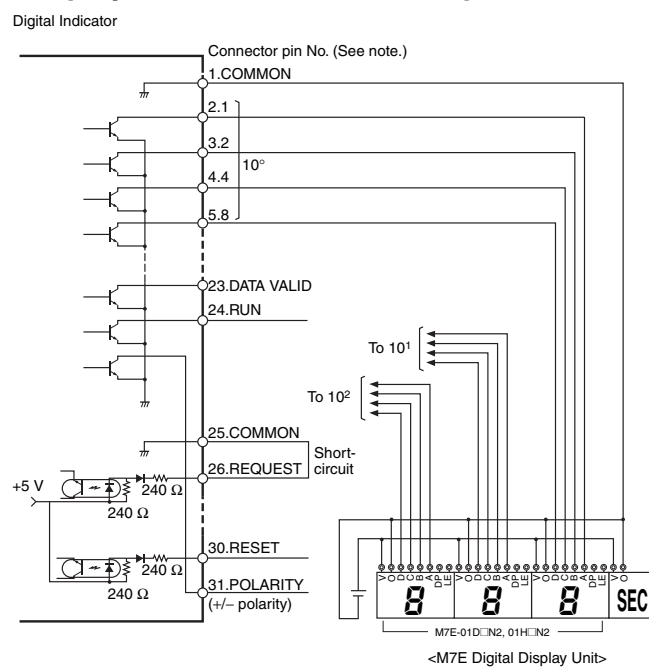
Measurement data is output every 64 ms while the REQUEST signal remains ON.

Note: If HOLD is executed when switching between data 1 and data 2, either data 1 or data 2 is output depending on the timing of the hold signal. The data will not go LOW.

Programmable Controller Connection Example



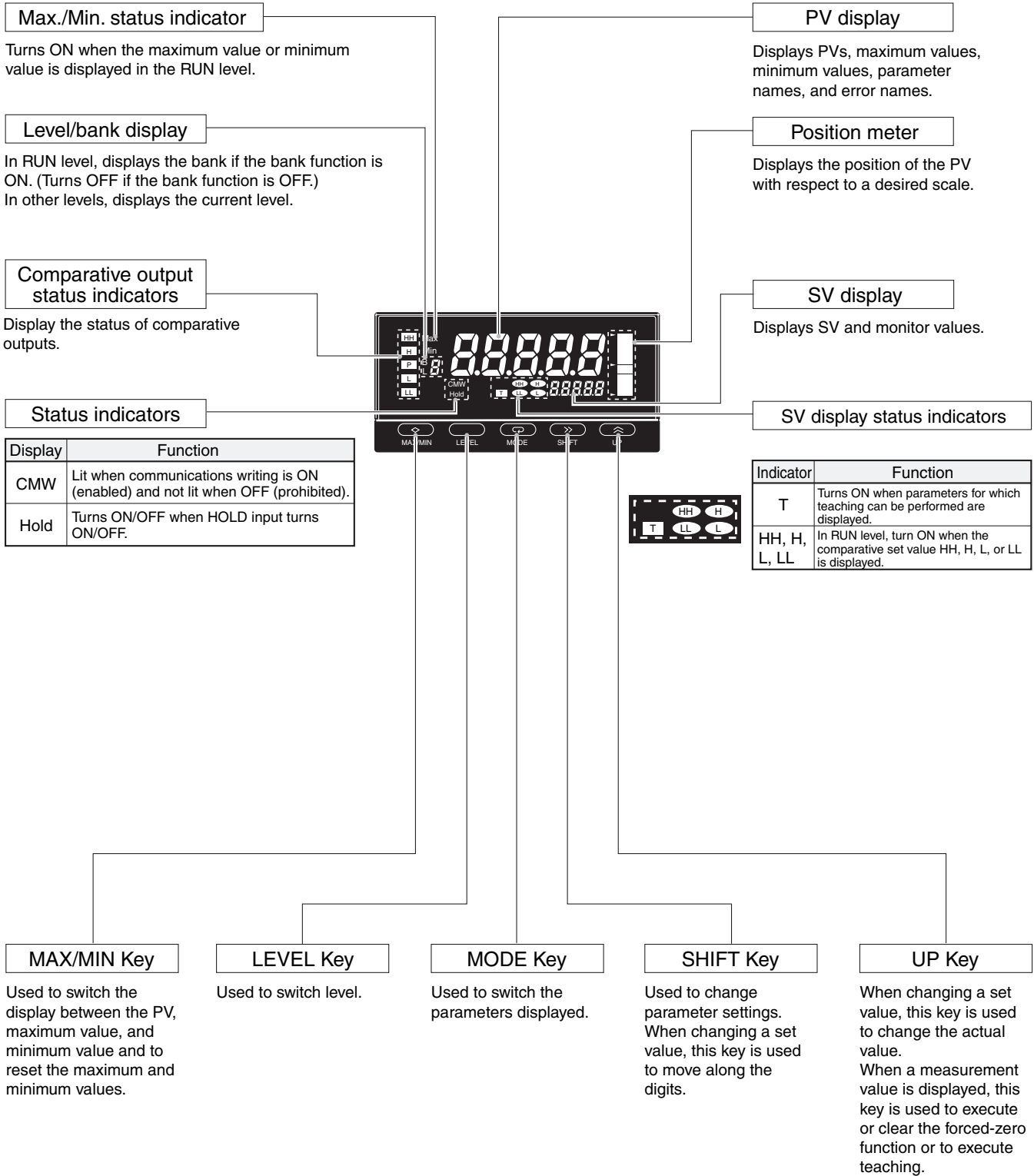
Display Unit Connection Example



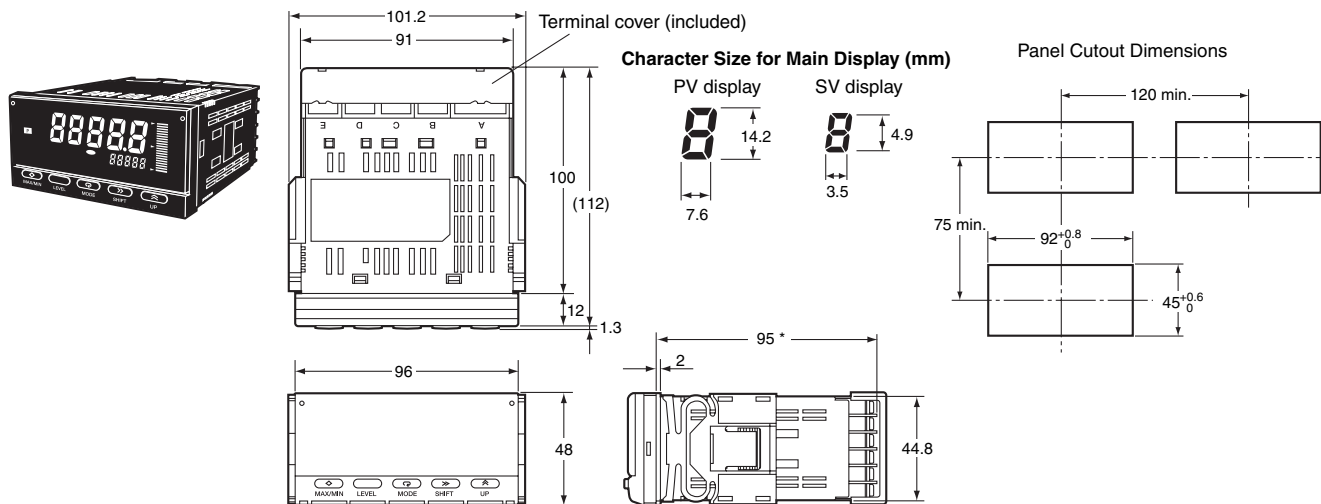
Note: The BCD output connector pin number is the D-sub connector pin number when the BCD Output Cable (sold separately) is connected. This number differs from the pin number for the Digital Indicator narrow pitch connector (manufactured by Honda Tsushin Kogyo Co., Ltd.).

Refer to the following User's Manual for application precautions and other information required when using the Digital Indicator:
 K3HB-R/P/C Digital Indicator User's Manual (Cat. No. N136)
 The manual can be downloaded from the following site in PDF format: OMRON Industrial Web <http://www.fa.omron.co.jp>

■ Component Names and Functions



■ Dimensions



*DeviceNet models: 97 mm

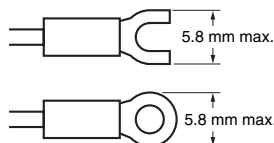
Terminal: M3, Terminal Cover: Accessory

Wiring Precautions

- For terminal blocks, use the crimp terminals suitable for M3 screws.
- Tighten the terminal screws to the recommended tightening torque of approx. 0.5 N·m.
- To prevent inductive noise, separate the wiring for signal lines from that for power lines.

Wiring

- Use the crimp terminals suitable for M3 screws shown below.



Unit Stickers (included)

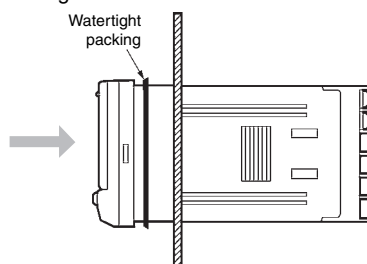
- No unit stickers are attached to the Digital Indicator.
- Select the appropriate units from the unit sticker sheets provided.

V	A	√A	A	%	J	Pa	Ω
s	/	N	m	W	°C	m ³	k
°F	g	min	mm	rpm			
VA	mV	mA	Hz				
m/min	OMRON						
OUT	OUT						

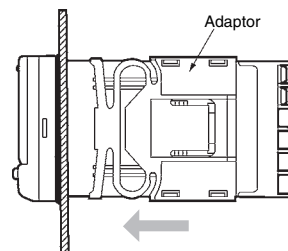
Note: For measurements for commercial purposes, be sure to use the unit required by any applicable laws or regulations.

Mounting Method

1. Insert the K3HB into the mounting cutout in the panel.
2. Insert watertight packing around the Unit to make the mounting watertight.

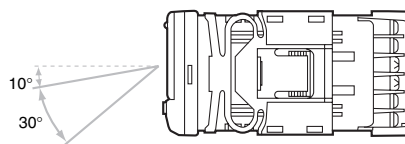


3. Insert the adaptor into the grooves on the left and right sides of the rear case and push until it reaches the panel and is fixed in place.



LCD Field of Vision

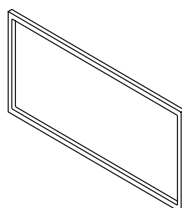
The K3HB is designed to have the best visibility at the angles shown in the following diagram.



Rubber Packing (Sold Separately)

K32-P1

If the rubber packing is lost or damaged, it can be ordered using the following model number: K32-P1.



(Depending on the operating environment, deterioration, contraction, or hardening of the rubber packing may occur and so, in order to ensure the level of waterproofing specified in NEMA4, periodic replacement is recommended.)

Note: Rubber packing is provided with the Controller.

Main Functions

■ Main Functions and Features

Measurement

Function *FUN*

The K3HB-R has the following six functions for receiving and displaying input pulses.

F1: Rotation (rpm)/circumferential speed

F2: Absolute ratio

F3: Error ratio

F4: Rotational difference

F5: Flow rate ratio

F6: Passing time

The K3HB-P has the following six functions for receiving and displaying input pulses.

F1: Passing speed

F2: Cycle

F3: Time difference

F4: Time band

F5: Measuring length

F6: Interval

The K3HB-C has the following three functions for receiving and displaying input pulses.

F1: Individual inputs

F2: Phase differential inputs

F3: Pulse counting input

Filters

Average Processing *AVG-t, AVG-n*

Average processing of input signals with extreme changes or noise smooths out the display and makes control stable.

Input Types *IN-tA, IN-tB*

Specify the types of sensor connected to input A and input B.

Input Compensation

Auto-zero Times *At.3A, At.3b*

The frequency is forced to zero if there is no pulse input for a set period.

Key Operations

Teaching

The present measurement value can be used as a scaling value.

Key Protection

Key protection restricts level or parameter changes using the keys to prevent unintentional key operations and malfunctions.

Outputs

Comparative Output Pattern **ōūē-P**

Standard, zone, and level comparative output patterns can be selected for comparative outputs.

Hysteresis **HYS**

Prevents comparative outputs from chattering when the measurement value fluctuates slightly near the set value.

Output Refresh Stop **ō-SēP**

Holds the output status when a comparative result output other than PASS turns ON.

PASS Output Change **PRSS**

Comparative results other than PASS and error signals can be output from the PASS output terminal.

Output OFF Delay **ōFF-d**

Delays turning OFF comparatives for a set period. This can be used to provide sufficient time to read the comparative output ON status when the comparative result changes at short intervals.

Shot Output **SHōē**

Turns ON the comparative output for a specific time.

Output Logic **ōūē-n**

Reverses the output logic of comparative results.

Startup Compensation Timer **S-tōr**

Measurements can be stopped for a set time using an external input.

Output Test **tēēē**

Output operation can be checked without using actual input signals by using the keys to set a test measurement value.

Linear Outputs **LSEēL, LSEēM, LSEēH, LSEēL**

A current or voltage proportional to the change in the measurement value can be output.

Standby Sequence **SēdbY**

The comparison outputs can be kept OFF until the measurement value enters the PASS range.

Display

Display Value Selection **dēSP**

The display value can be set to the present value, the maximum value, or the minimum value.

Display Color Selection **ēōēōr**

The present value display color can be set to green or red. The color of the present value can also be switched according to the comparative output.

Display Refresh Period **dēEF**

When the input changes rapidly, the display refresh period can be lengthened to control flickering and make the display easier to read.

Position Meter **PōS-t, PōS-H, PōS-L**

The present measurement value can be displayed as a position in relation to the scaling width on a 20-gradation position meter.

Prescale **PSRō, PSRY, P5.bō, P5.bY**

The input signal can be converted and displayed as any value.

Comparative Set Value Display **Su.dSP**

Select whether or not to display the comparative value during operation.

Display auto-return **rēē**

Automatically returns the display to RUN level when there are no key operations (e.g., max./min. switching, bank settings using keys).

Other

Max./Min. Hold

Holds the maximum and minimum measurement values.

Bank Selection **bnY-ē**

Switch between 8 comparative value banks using the keys on the front panel or external inputs. A set of set comparative values can be selected as a group.

Bank Copy **ēōPY**

Any bank settings can be copied to all banks.

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.

To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

In the interest of product improvement, specifications are subject to change without notice.